OPTICAL AND INTERFEROMETRIC STUDIESOF
GROWTH PHENOMENA ON CARBORUNDUM CRYSTALS$B Y$
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THESIS
PRESENTED FOR THE DEGREE OF
DOCTOR OF PHILOSOPHY
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## ABSTRACT.

The theory of the growth of a perfect crystal is outlined and a brief description is given of the development of this theory, taking into account the presence of imperfections, especially dislocations, in the crystal. The molecular 'growth spirals' and other features predicted by this theory put forward by Burton, Cabrera and Frank require improved experimental techniques for their study, which are described. The experimental study of the growth features divides itself into two parts:-
(1) Microscopic studies
(2) Interferometric studies.

The different growth features observed on the faces of silicon-carbide (Si-C) crystals are illustrated and explained. The observed 'growth spirals' can be divided into three types:
(1) Elementary spirals with step heights equal to the size of the X -ray unit cell
(2) Spirals originating from dislocations of multiple strength, the step heights being a multiple of the X-ray unit cell
(3) Interlaced spirals in which the step heights are a fraction of the unit cell.

The microscopic studies illustrate the information about the shape of the spirals, the behaviour and interaction of growth fronts with one another, originating from different sources, the growth pattern for a number of screw dislocations emerging on the crystal face,fault surfaces, and their statisscal properties such as density of dislocations etc. From these studies the type of information obtainable about the conditions of growth is the size of the critical nucleus and the supersaturation.

The interferometric techniques utilized for the measurement of step heights are discussed. A study of the measured step heights leads to an understanding of the interesting property of 'polytypism' as observed in silicon-carbide crystals which occur in different types as shown by X-ray diffraction data. The 'growth spirals' demonstrate the X-ray predictions and confirm them.

For convenience in comparing the Text and the Figures, the Thesis
has been bound in two separate

## Volumes.

Vol. 1. The Text.
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PART I.

## CHAPTER I.

## THFORY OF THFH GROWIHH OF A PISRIFBCT CRYSTAL.

### 1.1. INTRODUCTION.

The history of the theory of crystal growth divides itself into two parts. Firstly, the theory of the growth of an ideally perfect crystal and secondly the growth of real crystals which are imperfect. The essential ideas of the growth of perfect crystals were first formulated by Gibbs (1878). This theory has been developed during the last thirty years by Volmer (1920 onwards), Kossel (1927), Stranski (1928), Becker and Dひ̈ring (1935) and Frenkel (1945, 1946). Burton, Cabrera and Frank (1949, 1951) who have reexamined some aspects of the earlier theory, have developed a theory of crystal growth which takes into account the presence of imperfections, especially dislocations. The experimental observations of the present investigation are connected with the latter theory, and have not only confirmed many of its predictions but have also supplemented them with new facts. However, for the sake of continuity, a brief account of the theory of the growth of a perfect crystal will be given, no attempt being made to discuss this extensive and well-developed quantitative theory. Instead the subject will be presented more from a geometrical and pictorial point of view,
emphasizing those results which have a bearing on the later theory in which the dislocations play such an important role.

### 1.2. GROWTH OF A PERFECT CRYSTAL.

A crystal of any shape may be considered as being bound by close-packed planes of atoms containing steps. The surfaces which coincide with close-packed planes are the only ones which are planar in the sense that all the surface atoms lie on a plane. The vicinal faces may be regarded as close-packed planes separated by steps. For the purpose of illustrating the growth of a perfect crystal, the simple Kossel model may be considered, the molecules being taken as cubes which/stacked face to face. Each cube is attracted equally by all its six neighbours and only the nearest neighbours attract one another.

The structure of any low-index face of a perfect crystal at the absolute zero of temperature at which there are no thermal vibrations may be shown as fig. ( $1+1 a$ ), which represents the profile of a completely flat surface partially covered by another molecular layer. The boundary line where there is a difference of level equal to an intermolecular spacing between the two sides of the line is called a step on the crystal surface. In general this step will also be incomplete, giving a "kink" of the type marked 'A' in fig. ( $\mid a)$, in the step. As shown below, these
"kinks" play an important part, by acting as "exchange sites" in the positioning of new molecules in the building up of the crystal in order to complete a new layer.

As the temperature is raised from absolute zero, the component molecules will start vibrating relative to one another, the vibrations becoming progressively stronger as the temperature is increased. Soon molecules will be shaken from the crystal and will fly about in the space surrounding it. These free molecules constitute the vapour. Thus there will be a certain vapour concentration (average number of vapour molecules per unit volume) in contact with the crystal surface. Those molecules which are at the "kink" positions are more likely to leave the crystal and vapowize, though this will also happen for some molecules at other positions. This can be pictured in the above model, since the molecules at the "kinks" are bound only by three molecules, whilst those on the straight portions of the step are bound/four and those on the flat portions of the surface by five. The energy needed for a molecule to leave the "kink" position such as $A$ is equal to the evaporation energy $W$. Two processes will occur simultaneously; while some molecules will be leaving the crystal, others will be arriving at the crystal from the vapour. An equilibrium state is reached when the rates of these two processes are equal. The surface will now look
more like fig. (2), having changed from fig. (la) in two ways. Firstly the step has acquired a number of kinks such as $A$. Secondly a small number of molecules have been adsorbed on the crystal surface and on the step, shown in fig. (2) as $B$, and also a similar number of surface vacancies C, a smaller number of pairs of adsorbed molecules $D$ or pairs of vacancies have been created. Aggregates of larger numbers of molecules may also be formed but their proportion will be progressively smaller, as the number of molecules in the aggregate increases.
(i) Frenkel (1945), Burton and Cabrera (1949, 1951) have studied the structure of a monomolecular step and have calculated the number of kinks per unit length. These kinks will be of two kinds, one may be called a positive and the other a negative kink. Suppose the step is along the $x$-axis, following it along the direction of increasing $x$, points where $y$ increases or decreases by a unit spacing 'a', the intermolecular distances, are called positive and negative kinks respectively. They have shown that if $n_{+}$and $n_{-}$is the number of kinks of opposite sign per atomic spacing measured along the nearest principal direction, then in equilibrium

$$
n_{+} n_{-}=\exp (-2 w / k T) \cdots \cdots(1)
$$

where $\mathcal{W}$ is the energy necessary to form a kink, $T$ is
the absolute temperature, $k$ is the Boltzman's constant. They estimate $w$ to be of the order of $\frac{W}{12}$, 'where $W$ is the evaporation energy.

The mean distance $x_{0}$ between the kinks is given in terms of ' $a$ ', the interatomic distance by

$$
\begin{aligned}
x_{0} & =\frac{1}{2} a\{\exp (w / k T)+2\} \cdots . . . . . .(2) \\
& \sim \frac{1}{2} a \text { exp. }(w / k T)
\end{aligned}
$$

Introducing $\phi$, the nearest neighbour interaction, which is related to the evaporation energy $W$ by the equation

$$
\phi=\frac{1}{6} w \quad \cdots \cdots \cdots \cdot(4)
$$

Equation (3) may be written as

$$
x_{0}=\frac{1}{2} a \exp (\phi / 2 k T) \quad \cdots \cdots \cdots(5)
$$

For growth under typical conditions, which may be taken as such that the temperature lies between 0.5 and 0.8 times $T_{b}$, the boiling point in degrees $K, \phi / k T \sim 4$ and equation (5) gives

$$
x_{0} \sim 4 a \quad \cdots \cdots \cdot \cdots \cdot(6)
$$

This concentration of kinks in the steps will remain
practically unchanged even if the vapour is supersaturated.
(ii) The proportion $n_{s}$ of the surface sites covered by adsorbed molecules has been given by Burton, Cabrera and Frank (1951) as approximately

$$
\begin{equation*}
n_{s}=\exp \left(-W_{s} / k T\right) \tag{7}
\end{equation*}
$$

where $W_{s}$ is the energy required to transfer a molecule from a site $A$ to the plane surface. They have estimated $W_{s}$ to be about $\frac{1}{2} W$.

It was first realized by Volmer that adsorbed molecules diffuse with considerable ease over the crystal surface. Therefore, the process of growth of a crystal surface with steps will be the result of three processes. Firstly, a transport of molecules from the vapour to the adsorbed layer. Secondly, the diffusion of adsorbed molecules towards the steps. Thirdly, the diffusion of adsorbed molecules along the edge of the steps towards a kink. These processes are shown pictorially in fig. (1). The mean displacement $x_{s}$ of adsorbed molecules, which is the average distance a molecule wanders on the crystal surf ce between the time it hits the surface and the time it evaporates again is given according to Burton, Cabrera
and Frank (1951) by the equation

$$
\begin{equation*}
x_{s}=a \exp \left\{\left(W_{s}^{\prime}-U_{s}\right) / 2 k T\right\} \tag{8}
\end{equation*}
$$

where $U_{s}$ is the activation energy for surface diffusion i.e. for migration from one surface site to another, and this has been estimated to be of the order of $\frac{1}{20} \mathrm{~W}$; $W_{s}^{\prime}$ is the evaporation energy from the surface to the vapour and is given by $W_{s}^{\prime}=3 \phi$ i.e. half the total evaporation energy $W$. From this, neglecting $U_{S}$, we can estimate that

$$
x_{s} \sim a \exp (3 \phi / 2 k T) \ldots \ldots-(9)
$$

which is $\sim 4 \times 10^{2} a$ $\ldots-\ldots-(10)$ for typical values of $\phi / k T \sim 4$.

This shows that $x_{s} \gg a$ from which it follows that in growth from the vapour, the rate of direct arrival of molecules from vapour at any particular point on a crystal surface is generally small as compared with the rate of indirect arrival by way of surface migration.

The points where growth actually occurs are the kinks in the steps. This can be pictured again in the above model, for, when an atom meets a step, it is held
at the step where it is more tightly bound to the crystal, being in contact on two of its six sides. However, it continues to diffuse along the step until it hits a kink or re-entrant angle, where it makes three bonds with the crystal. When the crystal is in equilibrium with the vapour, molecules join and leave these points with equal frequency. The rate of departure depends only on the temperature while the rate of arrival is proportional to the vapour concentration. Hence when the vapour pressure is increased above the equilibrium value, more molecules join kinks than leave them and so the step advances. The velocity $v_{\infty}$ of a 'straight step' is given by Burton, Cabrera and Frank (1951) as

$$
v_{\infty}=2 \sigma x_{s} Z \beta \quad \ldots-\cdots-\cdots(11)
$$

Where $Z$ is the frequency with which the molecules from the equilibrium vapour strike a lattice site in the surface; $\beta$ is a factor which is unity in simple cases, and $\sigma$ is the supersaturation defined by

$$
\sigma=\alpha-1 \quad, \quad \alpha=\frac{p}{p_{0}}
$$

$$
------(12)
$$

in which $p$ is the actual vapour pressure and $p_{0}$ the saturation value, $\propto$ being called the saturation ratio. Qualitatively this means that all molecules which hit the surface in the "diffusion zone" of width $2 x_{s}$ will reach the advancing step and since there is a large
concentration of kinks (ie. exchange sites) in the step they will be adsorbed.

A curved step with a radius of curvature
 advances with a velocity $v_{\rho}$ given by

$$
v_{p}=v_{\infty}\left(1-\frac{p_{e}}{p}\right) \quad-\cdots-\cdots-\cdots-(13)
$$

where $P_{c}$, the radius of critical nucleus defined by equation $(16)$ is given by

$$
p_{c}=a \phi / 2 k T \ln \alpha \quad---\cdots--(16)
$$

Thus all the steps initially present on the surface of the crystal, during the process of growth will travel towards the edge of the crystal and disappear forming a completed surface, which will contain a few adsorbed molecules and perhaps a few vacancies. Any further growth will be possible only if now steps can be formed.

### 1.3. SURFACE NUCIEATION.

Frenkel (1945) extended the idea of the formation of kinks in a step to the formation of steps on a perfect crystal face, in a similar way. Detailed calculation by Burton and Cabrera (1949,1951) shows that steps will not be created by thermodynamic fluctuations on a low-index face unless the temperature is close to the melting point,
when the surface rapidly becomes rough. Therefore, for the growth to continue, steps must be formed, gradually, if at all, at ordinary temperatures.

Gibbs (1878) first appreciated that this requires the initiation of a new layer which is a nucleation process. Before a new layer can grow, a nucleus or an island monolayer of the type shown in figs. (1 \& 3) must be formed on the surface. The problem of nucleating an island monolayer on a close-packed crystal surface is similar to the familiar problem of nucleating a water droplet. For a given supersaturation, there is a critical radius $P_{c}$ of the nucleus (assuming it to be circular), such that a nucleus of radius greater than $P_{C} \quad$ will grow and if less, it will evaporate. This arises because the line energy of the step of the island monolayer causes a local equilibrium vapour pressure which is inversely proportional to its radius of curvature. Thus a nucleus with a small radius of curvature has a high equilibrium vapour pressure. Hence, the supersaturation which is the excess of ambient vapour pressure over the equilibrium pressure is less; and for a sufficiently small nucleus, the supersaturation may actually be negative so tha $t$ the nucleus evaporates. The formation of a new layer thus depends upon improbable fluctuations among aggregates of adsorbed molecules ultimately producing a critical nucleus. The probability
of this occurrence was first calculated by Becker and DUring (1935) on the assumption of a rectangular nucleus and is of the form

$$
Z\left(S / s_{0}\right) \exp \left(-A_{0} / k T\right)
$$

$$
-------(14)
$$

where $Z$ is essentially the rate of arrival of fresh molecules at single surface lattice sites; $S$ is the surface area of the crystal face under examination; So is the area per molecule in the layer; and $A_{0}$ is half the total edge free energy of the critical nucleus and is given by

$$
A_{0}=\frac{2 p_{c} \phi}{a}
$$

$$
------(15)
$$

In the simple case of a circular nucleus $\rho_{C}$, the radius of the critical nucleus is given by

$$
\rho_{c}=a \phi / 2 k T \ln \alpha \quad-\cdots \cdots(16)
$$

and therefore

$$
A_{0}=\phi^{2} / k T \ln \alpha . \cdots-\cdots(17)
$$

Recently Burton, Cabrera and Frank (1951) have reexamined the theoretical basis of this equation with a more detailed consideration of the shape of the nucleus in various stages of growth, and the influence of molecular diffusion on the surface of the crystal. They concluded
that apart from an unimportant numerical factor, the formula ( 14 ) is a correct deduction in view of the assumption made.

To make an estimate of this probability typical numerical values can be substituted in formula (14). $Z$ cannot exceed $10^{13} \sec ^{-1}$ even in a dense environment, therefore, for a crystal of millimetric dimensions, the whole factor outside the exponential must be less than $10^{27}$; generally it is about $10^{22}$. For any observable growth rate on the time scale of a laboratory experiment (say $10^{-3}$ layers per sec.i.e. 1 micron per month), it follows that $\ln \alpha$ must be at least $\left(\frac{\phi^{2}}{k T}\right) / 90$ which with typical value of $\phi / k T$ signifies a supersaturation of at least $25 \%$ to $50 \%$. Thus the nucleation rate is an extremely sensitive function of supersaturation. Above this critical supersaturation, the growth rate would increase rapidly with supersaturation, the process not being limited by nucleation. Below this critical supersaturation, the probability of nuclei formation would become rapidly negligible.

These theoretical conclusions are however, not in agreement with experimental observations. Volmer and Schultze (1931) trying to verify this result studied the growth rate of individual iodine crystals in slightly supersaturated vapour at $0^{\circ} \mathrm{C}$.

They found the growth rate proportional to the supersaturation down to a value of $1 \%$. Only below this degree of supersaturation did it fall below proportionality and then not abruptly.

On the other hand, the observations of Haward (1939) are in agreement with the theory of suface nucleation. He studied the deposition of several sublimable solids like $\mathrm{Hg}_{2}$ on a metal surface, coated with a previous deposit of the same substance. This coated metal target was subjected to a vapour 'beam' of controlled intensity at a fixed temperature. Using a weighing technique to measure the mean overall rate of deposition, the theory of surface nucleation was verified.

There are, however, no other known experiments of this kind. In general for those crystals which grow, the growth rate is proportional to supersaturation down to values much lower than the theoretical supersaturation of surface nucleation theory.

### 1.4. SUMMARY.

To summarize then, the position is as follows.
Any crystal face with a step will continue to grow because of the high concentration of kinks in it created by thermal fluctuations. During the process of growth
this step will travel to the edge of the crystal and thus disappear leaving a complete crystal surface. When all the steps have been eliminated by advancing and forming complete layers, further growth will continue only if new steps can be formed. Now on a low-index face, steps cannot be created by thermodynamic fluctuations in the same way as the creation of kinis in a step, below a certain critical temperature which is close to the melting point. Thererore, for further growth on low-index faces, steps must be formed gradually at ordinary temperatures by some mechanism. This can happen by the formation of a two-dimensional nucleus or island of molecules, the edges of which will provide the necessary steps. It has been shown that the probability of the formation of nuclei is a very sensitive function of supersaturation and is quite negligible below a certain critical value which for typical values of the constants involved is of the order of $25 \%$ to $50 \%$. However, real crystals grow at obser vable rates at supersaturations of $1 \%$ or lower - infact the most regular and well developed crystals are obtained at low supersaturations. At these low supersaturations the probability of the formation of nuclei is negligible.

This, therefore, leads us to the conclusion that the growth of crystals at low supersaturations can only be explained by recognizing that real crystals ape not perfect.

This idea first introduced by Frank (1949; Burton et al. 1949, 1951) for the growth of a crystal, provides us with another mechanism by which a surface remains stepped no matter how far the steps advance. Therefore, the growth of the crystal face will continue. In the following chapter a description of the development of this theory will be given.

## CHAPTER II.

## GROWTH OF AN IMPERFECT CRYSTAL

### 2.1. DISLOCATIONS

Smekal first pointed out that an important difference in the properties of crystals is related to the distinction between ideal and real crystals. Certain properties of crystals which are essentially independent of crystal defects were designated by him as structureinsensitive, whilst those depending upon the presence of defects were called structure-sensitive properties. Among the structure-insensitive properties, may be named the specific heat, elasticity, thermal expansion and compressibility, the energy of formation, the principal features of optical absorption (colour) and dispersion, and finally dia - and para magnetism. The important structure sensitive properties are, diffusion phenomena, the ionic and electronic conductivity in insulating crystals and semi-conductors, the internal photo-effect, plasticity, and crystal strength.

The imperfections introduced to explain these structure sensitive properties of a real crystal, are of three different types. The first type of crystal defect consists of lattice flaw where foreign atoms have taken up the normal positions of the atoms in the crystal lattice, a vacant site may be said to be a special case of this. The second type is known as interstitial atoms. These consist
of either foreign atoms or atoms of the crystal material, outside the regular geometrical positions in the crystal lattice. The third type which is called dislocations, consists of purely geometrical faults in the crystal lattice. Of these, only the last type has any effect on the lattice at distances greater than a few inter-atomic spacings.

The concept of a dislocation arises naturally as a result of the crystallographic nature of plastic flow. It is observed in strained metals that slip lines mark important crystal planes and the plastic strains can be resolved into simple shears along these planes, the plastic flow being determined by the shear stress. Furthermore, gliding occurs in the direction of closest atomic packing in the glide plane and not in the direction of maximum resolved shear stress. Therefore, this shows that the plastic flow occurs by the sliding of certain atomic planes called slip planes, the structure of which remains crystalline during flow.

Now, if we consider a plane of atoms $A$, sliding in a certain crystallographic direction across a neighbouring plane $B$, different portions of $A$ will, in general, slip over $B$ by different amounts. This will be so, because the atoms in a crystal are not rigidly bound to each other but are elastically coupled so that thermal vibrations and local irregularities will make the forces acting over the glide
planes non-uniform. A boundary may be pictured such that on either side of this, the two planes $A$ and $B$ have slipped by different amounts. The type of line discontinuity marking this boundary is called a dislocation. There are two standard types of dislocations, the 'edge' and the 'screw' dislocation, with a series of intermediate cases which can be regarded as composed of these two standard types. An excellent account of the theory of dislocations has been given by Cottrell (1949). These dislocations will be briefly illustrated by simple models.

### 2.2. EDGE DISLOCATIONS

The type of dislocation which was first introduced by Taylor (1934) Polanyi (1934) and Orowan (1934) is called the 'edge' dislocation. This may be pictured as follows. Consider a block of crystal (fig. (4) ) in which the lower half of the crystal is pulled with respect to the upper half in the direction shown by arrows. The result is shown in fig. (4 7. We see that the part A B E F has slipped in the direction $A \cdot{ }^{\prime} '^{\prime}$ and the part E F D C has remained unslipped. E F marks the boundary between the two regions which have slipped by different amounts and is the dislocation line. The atomic structure in the side plane perpendicular to EF is shown in fig. (5). It will be seen in fig. (5) that atoms in the upper half crystal $P$ are compressed along the slip direction and those in the lower half $Q$ are extended. The
situation is analogous to the insertion of an extra half plane of atoms from above. The dislocation line lies at the edge of this plane and hence its name. It will be observed that the dislocation line E F is perpendicular to the slip direction $A^{\prime} F^{\prime}$.

Dislocations can also exist which are the inverse of that shown in figs. (4) and (5), and will be created when the extra half plane of atoms is inserted from below instead of from above. These two types are called the positive and negative dislocations. Since, by inverting the diagram, or crystal, a positive dislocation can always be turned into a negative one or vice versa, this distinction would be trivial. The real distinction between the positive and negative dislocations is given by the forces exerted between the dislocations, since dislocations which are of the same sign repel each other while those of unlike sign attract one another.

### 2.3. SCREW DISLOCATI ONS

The second type of dislocation was first introduced by Burgers (1939) and is called a screw dislocation. This may again be illustrated by a crystal model. A cut A B E F is made in the crystal (fig. (6) ) and the crystal material to the right of the cut is pushed down by one molecular diameter. The result is shown in fig. (7). A step has now
been created, on the surface of the crystal such that on the left hand side, the plane of the crystal surface is higher and on the right hand side it is lower. The step does not extend throughout the surface of the crystal but extends only from the point $F$ to the edge of the crystal. The line EF is the boundary line between the right and left parts of the crystal which have slipped by unequal amounts and hence is the dislocation line. The model of fig. (8) illustrates the arrangement of molecules for a dislocation line meeting the surface of the crystal at right angles. The molecules in the crystal no longer lie on planes as in the ideal lattice but are continuously displaced. At distances larger than a few intermolecular distances from the dislocation line, the crystal deviates very little from perfection: only very near the dislocation line some irregularity seems to appear. In fig. (9) showing arrangement of molecules in the slip plane A B C D, a part A BEF of this plane has slipped in the direction E F, while the remainder F E C D has not slipped. In fig. (9) the dotted lines and circles, represent the molecules to the left of the slip plane whereas the molecules to the right of the slip plane are represented by full lines and circles. It may be pointed out that the dislocation line E F is parallel to the slip direction.

A route may be considered on any lattice plane of the crystal, along a line drawn through nearest neighbouring
atoms in such a way that it forms a closed plane loop. Such a line is called a Burgers circuit. If by tracing the line in the real lattice, corresponding to the circuit in the perfect lattice, this line does not form a closed loop, then a geometrical fault of the dislocation type is present. The vector required to complete the Burgers circuit is called the resultant Burgers vector of the dislocations encircled.

This may be pictured in the above model of figs. (7 \& 8) by considering a route taken from the top of the step, going round the dislocation point F back to the bottom of the step. We have followed a path on the surface of the crystal which was flat before the creation of the dislocation, and instead of finishing at the starting point we finish one molecule beneath it. In order to complete the Burgers circuit i.e. to reach the starting point, a vector equal to the height of the step is needed. Burgers gave the name "dislocation strength ${ }^{\text {" }}$ to the modulus of this vector.

The crystal containing one screw dislocation is not built of molecular layers stacked on top of each other as in ideal case, but instead consists of a single molecular plane in the form of a helicoid of a spiral staircase and hence the name screw dislocation; the dislocation line being called its axis.

The Burgers vector is independent of the distance of
the Burgers circuit from the disloca.tion, giving evidence only of the total effect of the dislocations encircled. Pairs of dislocations of equal but opposed Burgers vector may escape detection unless the Burgers circuit is taken as small as possible. A more detailed description of the general behavigur of the Burgers circuit has been given by Frank (1951). Since the Burgers circuit can be continuously displaced along the dislocation line without change in its Burgers vector, a dislocation cannot terminate within the crystal.

The screw dislocation may be either of the righthanded or the left-handed type. In the right-handed type, moving along the Burgers circuit from a higher to a lower level, the route will be clockwise, whereas in the lefthanded type it will be anticlockwise. The right-handed dislocation will be obtained when the crystal material to the right of the cut A B E F (fig. 7) has been pushed down with respect to the other, the inverse operation will create a left-handed screw dislocation. Since these dislocations may be turned into one another by turfing the crystal, this distinction would again be trivial, but as before it is the forces exerted between the dislocations that distinguish them - like dislocations repel and those unlike attract each other. As is shown in the next section right-handed and lefthanded screw - dislocations give rise to 'growth spirals' which are clockwise and anticlockwise respectively. This
distinction is of importance when growth fronts originating from different sources interact with one another.

### 2.4. GROWTH SPIRAI

The dislocations that take part in the growth of a crystal are of the screw type. As seen in the last section, a. screw dislocation emerging on the face of a crystal provides it with a step. This step is self perpetuating in the sense that when one, two or any number of layers of atoms have been laid down on the crystal surface, the step remains. Hence the steps needed for the growth of a crystal are provided by the screw dislocations and the need of two dimensional nucleation never arises. This offers an explanation to the observed growth of crystals at low supersaturations.

The process of growth under these circumstances in the presence of screw dislocations will be similar to that outlined for a perfect crystal with a step. The step provided by the screw dislocation will have kinks as before and when the atoms are adsorbed on the crystal surface, they diffuse to the step and finally to the kinks where they are adsorbed for the building up of the crystal and the step will advance. In the case of a perfect crystal the step extended all the way across the crystal surface so that it could advance parallel to itself, thereby completing a new layer. However, the step provided by the emergence of a screw dislocation, terminates at the dislocation point, where it remains fixed.

Hence, when growth takes place, the step can advance only by rotating round the dislocation point somewhat like the hand of a clock. At a particular supersaturation each point on a straight step will advance with the same speed, therefore, the section of step near the dislocation will have a higher angular velocity for the same linear velocity and consequently make a larger/number of revolutions in a given time than the sections further out. Thus the step will wind itself into a spiral. Actually, for the section of the step near the centre because of the higher curvature there will be a higher equilibrium vapour pressure and therefore a lower local supersaturation, so that its rate of advance is slower and its curvature is everywhere less than $\rho_{e}^{-1}$, as seen from equation (13). When the steady state has been reached, the whole spiral will rotate uniformly about the dislocation. Several stages of the development of a growth-spiral are shown in fig. (10) which shows the top of the crystal in fig. (8) looking from above. In fig. (10) the spiral has been drawn as a smooth curve. The exact shape of the spiral and the more complex shapes arising from a number of dislocations is left to a later section.

These considerations, which were first put forward by Frank (1949), predict that on the surfaces of the crystals which have grown by this mechanism, flat molecular pyramids should be observed. An ideally long anneal would get rid of these dislocations but in practice some may always be expected
to remain. The available experimental evidence in support of this theory will now be given.

## CHAPTER III

## PAST OBSERVATIONS

### 3.1. DIFFICULTIES OF OBSERVATION

The elementary, molecular growth features (as distinct from gross growth features) are the ideally simple features which are easily interpreted by theory and are therefore likely to reveal considerable information about the mechanism of crystal growth. Therefore, it is only these molecular growth features, which have not been influenced by any accidental disturbances of growth, that have been studied in the present investigation.

Before the discovery of electron-microscope only optical instruments, such as a light microscope, were available to study these growth phenomena, for which purpose two resolutions of the instruments are required viz. the lateral resolution perpendicular to the direction of observation, and the resolution of depth. The depth resolution needed is of the order of a few Angstrom units and is characteristic of the crystal under examination, whereas the lateral resolution in an optical microscope is limited by the wave-length of light. Consequently the growth features had to be sufficiently far apart, to be resolved. This necessitates making observations on almost perfect crystals, molecularly flat over wide areas; such crystals are rare. After obtaining such a crystal, the problem stell remains to make visible these features only a few Angstrom units high. It is only recently that the optical 26.
techniques of multiple-beam interferometry and phase-contrast microscopy have developed sufficiently to make possible the study of such features.

The technique of electron microscopy is very superior for lateral resolutions but has only a limited resolution in depth probably of the order of $50 \mathrm{~A} \mathrm{e} \cdot \mathrm{g}$. the observation by Dawson and Vand (1951) of growth spirals of long-chain paraffins with step height equal to 47 A . This limitation will make it impossible to observe most of the growth features of step heights less than this. Naturally experimental observations of such growth features will be necessarily limited.

### 3.2. EARLIER OBSERVATIONS

Several workers have studied the surfaces of growing crystals. Marcelin (1918) and Kowarski (1935) studied the growth of m-toluidine from alcoholic solutions, which grws in extremely thin plates, thin enough to give interference colours. Discontinuities in the shade of interference colours, which meant discontinuities in thicknesses were observed to move across the surface of the crystal. It was calculated that some of these layers formed were only a few molecules in thickness. Volmer (1923) observed similar thin layers on thin crystals of $\mathrm{Pb} \mathrm{I}_{2}$ formed by mixing $\mathrm{Pb}\left(\mathrm{NO}_{3}\right)_{2}$ and KI solutions.

Bunn and Emmett (1949) studied a number of crystals
using dark ground illumination under high resolution and found that on fairly thick crystals of some substances layers several hundred Angstrom units high could be seen spreading across the face. On some crystals the layers were so thick that they could be seen by ordinary transmitted light or in birefringent crystals by using crossed nicols. Non-polar crystals were not observed to show layer formation and hence the studies were confined to ionic or polar crystals. As a result of their observations they found that layers often start from the centre of the faces spreading outwards, the thicknesses of the layers increasing as they approach the edges. At rapid growth the boundaries of these layers are irregular, but at slow growth these take regular shapes conforming to the symmetry of the crystal face. Disjolved impurities were observed to influence strongly the thickness and shape of the layers.

Evidence of the formation of surface nuclei was concluded from these observations and they thought that this process of layer formation observed for layers of thicknesses of several hundred Angstrom units would give the correct impression of what happens for molecular layers.

Instead of observing a crystal while it is growing, another approach for their study is to observe the surface of a crystal on which gowth has been arrested. The observation of such a crystal will reveal its history. In this latter
case of observation much better techniques can be employed and is therefore likely to yield more information. The present investigation comes under this category.

Growth pyramids of vicinal faces have long been observed and were recognized as a normal feature of slow growth (Miers (1903-4). Growth pyramids of this type can be seen on major rhombohedral faces of quartz crystals, but only limited information can be obtained from them since their structures cannot be resolved and bunching of steps is very frequent.

At the start of the present investigation, the only reported experimental data which demonstrated the growth of the crystals by spiral mechanism was that of Griffin (1950). He was the first to observe, using ordinary microscopy, line markings on the ( $10 \overline{1} 0$ ) faces of beryl crystals, which there is reason to believe are the edges of growth layers. Calibration by multiple-beam interference fringes has shown that the stepheight at these lines is less than 34 A i.e. less than four unit-cells - of the crystal. The behaviour of these steps around obstacles, where they neither split nor form multiple steps, suggests that each is like a unit step. Further these lines take the form expected from the edges of "monomolecular" growth terraces and in particular regions of the crystal face terminate in a manner which would be expected from the examination of a growth terrace terminating at a screw dis-
location: In addition, the observed patterns originating from a single and double screw dislocations correspond with the theoretically predicted shapes. From these facts, it was concluded that the observed steps are a unit cell high and thas the observed spiral was interpreted as a "growth spiral" in accordance with Burton, Cabrera and Frank's theory (1951).

Spiral markings on silicon-carbide crystals have been observed for some time past. Menzies and sloat (1929) reported such observations and more recently Padurow (1949) and Kalb and Wittborg (1951). But none of these workers has tried to offer any explanation as to the spiral formation, nor has any measurement of step height been made.

Thus the experimental position at the start of the present work was that the observations were meagre and qualitative. No exact measurement of the step height had been reported. In the interim period several other experimental observations have become available, and these are described in Chapter (XI) where the present position of the experimental observations is surveyed.

## PART II

SILICON - CARBIDE, ITS FORMATION, CRYSTAL -
STRUCTURE AND POIYPYPISM

FORMARTON OF SILICON-CARBIDE CRYSTALS, POIYYPISM AID NOTATIONS.
4.1. FORMATION OF SILICON-CARBIDE CRYSTALS. In 1890 Acheson tried to crystallise carbon by dissolving it in aluminium silicate in an electric arc, as a result blue crystals were obtained which were called carborundum. Analyses showed it to be Si-C. Later these crystals were made by reducing silica with carbon in an electric furnace. Naturally occurring Si-C crystals have been found as small hexagonal plates in a meteorite in Arizona, this mineral being called moissanite.

Best commercial grades of carborundum are pale green but various green and blue shades as well as black samples are common. Carborundum free from traces of iron is without colour. The cubic modification of silicon-carbide often occurs as yellow crystals, whereas the crystals of the rhombohedral and the hexagonal modifications occur in different colours and this colouring seems to be independent of the crystal modification (polytypism, see 4.2). It may be thought that the colouring is due to impurites. The considerable differences observed in the relatively low metallic conductivity of ©ifferent specimen's have also been attributed to impurities (Weigel 1915). The crystals studied in the present investigation were pale green, dark green, blue and black in colour.

The exact mode of the growth of silicon-carbide (Si-C) crystals is not known. The melting point of siliconcarbide has been estimated to be near $2230^{\circ} \mathrm{C}$ (Weigel 1915) and it will probably dissociate at that temperature, so that 31.
silicon-carbide crystals do not grow from their own vapour. Carbon and silica present inside the furnace, react at thet temperature, generating more volatile gases SiO and CO which supply $C$ and $S i$ needed for the growth of silicon-carbide crystals. It is thought that these gases will be adsorbed on the surface of the growing crystal and will undergo surface diffusion reacting with one another to form Si-C, the excess oxygen being removed as $\mathrm{CO}_{2}$ (or perhaps $\mathrm{O}_{2}$ ) which generates $C O$ on the hot carbon while $C O$ also reduces $\mathrm{SiO}_{2}$ to the relatively more volatile $S_{i} O$. The surface of the growing crystal may have a layer of combined oxygen; the state of the surface would vary with temperature and the $\mathrm{CO}-\mathrm{CO}_{2}$ balance in the atmosphere and would be quite complex. (Frank 1951a).
4.2. DIFFEREIN TYPES OF SILICON-CARBIDE CRYSTALS

## AND ${ }^{\prime}$ POLYMYPISM ${ }^{\prime}$

Silicon-carbide, which is strongly homopolar, occurs in over 12 known and possibly some more types. Among these, only one cubic form has been observed and there is no likelihood of anymore. This cubic form has a structure corresponding to $\beta-Z_{n} S$ (sphalerite) and hence it is suitably called $\beta-\operatorname{SiC}$. All the remaining types are called $\alpha-S_{i} C$ and are based either on hexagonal or rhombohedral unit cells. The basal pinacoid is predominantly developed and the crystals usually occur as hexagonal plates. The
opposite faces of the hexagonal plates differ in appearance in all modifications. One face is planar, the other often stepped, and it is on these plane faces that growth spirals have been observed. The various forms are so closely related to each other that a special term "polytypism" has to be used to distinguish it from the normal "polymorphism" (Baumhauer 1911, 1915; Thibault 1944); the various modifications being called the "polytypes" of silicon-carbide.

### 4.3. DESCRIPTION OF THE TYPES : RAMSDEIL'S NOTATION

The different polytypes of silicon-carbide were called type I, II, III etc., in the order of discovery, without referring to their crystal structure. As the number of the known types grew larger, it was soon realised that some designation, which will describe the type appropriately, had to be found out. Such a designation should be simple and accurate, and should describe the structure as fully as possible.

X-ray studies revealed that all types are composed of identical layers and differ only in their arrangement of these. Each type is uniquely distinguished by the number of layers necessary for the arrangement to repeat itself. Thus the total number of layers within the length of $c$ - axis for the types with the hexagonal unit - cell or thefrhombohedral types referred to the hexagonal unit may be taken to represent the type and Ramsdell (1947) added to this number the letter " $H^{\prime \prime}$ or " $R$ " depending upon whether the unit cell is hexagonal or
rhombohedral respectively. The different types are given in the table (I) and the unit cell constants as determined by X -ray methods are given in table II.

Table I
Ramsdell's Notation of Different Modifications.

| $\beta-S i C$ | $\alpha-\operatorname{Si} C$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| CUBIC | HEXAGONAL |  | RHOIBOHEDRAL |  |
| Notation | 01d Notation | $\begin{gathered} \text { Ramsdell's } \\ \text { notation } \end{gathered}$ | Old <br> Notation | $\begin{aligned} & \text { Ramsdell's } \\ & \text { Notation } \end{aligned}$ |
| $\beta-S i C$ | II | 6 H | I | 15 R |
|  |  | 4 H | IV | 21 R |
|  |  |  | VI. | 33 R |
|  |  |  | V | 51 R |

This notation uniquely distinguishes the different types and will be used for brevity in future. However, this notation does not reveal the geometry of the regular arrangement of the different layers in the unit cell. The different notations described below reveal this regularity in a simple manner.

Table II
Unit Cell Dimensions.

| Type | Hexag $a_{0}$ | 1 Cell | Rhombohedral Cell $a_{r h}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| 4 H | 3.073 A | 10.053A | - | - |
| 6 H | 3.073A | 15.079 A | - | - |
| 15 R | 3.073A | 37.70 A | 12.69A | $13^{\circ} 54 \frac{1}{2}^{\text {t }}$ |
| 21 R | 3.073A | 52.78 A | 17.683A | $9^{\circ} 58^{1}$ |
| 33 R | 3.073A | 82.94 A | 27.704 A | $6021{ }^{\prime}$ |
| 51 R | 3.073 A | 128.178A | 42.763 A | $4^{\circ} 07^{\prime}$ |
| $\beta-S i$ | Cubic | $=4.349$ |  |  |

### 4.4. INTERVAL SEQUENCE

Ott (1925) in his report of the type I, 15 layered rhombohedral crystal, described the structure in terms of the sequence of silicon (or carbon) atoms along the symmetry ates. In a given axis there are five atoms which are separated by layer intervals of 2, 4, 3, 4, 2. Thus the sequence (24342) was used to describe the structure. For the 33 and 51 layered rhombohedral types the interval sequences $\operatorname{are}(24243334242)$ and ( 24242433333424242 ) respectively. Not only does this interval sequence become
more and more unwieldy with the increasing number of layers in the unit cell, this method is not equally applicable to the hexagonal structures since for them the symmetry axes, are not all alike, the sequence along the 6-fold axis being different from that along the 3 -fold axis. Therefore, this notation gave place to more superior methods of describing the types.

### 4.5. CLASSICAL ABC NOTATION

The structure of silicon-carbide crystals may be described in terms of the close-packed layers of spheres. As is well known, equal spheres close-packed in a plane will lie with their centres at the corners of equilateral triangles each sphere touching six others in its own plane. All threedimensional close-packed structures may be regarded to be built up of layers of this sort. These layers when projected normally on a plane parallel to one of them fall into three possible positions, and may be labelled, A, B and C. The possible close-packings correspond to any sequence of these letters with no successive letters alike. The simplest form of close-packing is $A B A B A B$.... etc., and is the hexagonal close-packing. The arrangement $A B C$ ABC $A B C$.... etc., gives the cubic close-packing.

In each of the known structures of silicon-carbide crystals we have a silicon-lattice and an identical interpenetrating carbon lattice, which is displaced relative to the
other parallel to the c-axis, both structures being infinitely extended. Each carbon is tetrahedrally bonded to four silicon atoms and vice versa. The lattice of three modifications viz: 15R, 6H \& 4 H is shown in fig. (11). The c-axis is parallel to the vertical direction.

All silicon and carbon atoms lie on the symmetry axes, and all symmetry axes lie in the ( $11 \overline{20}$ ) planes. Therefore, the structure is most conveniently represented in a projection in the plane perpendicular to the c-axis. Since the carbon and silicon lattices are identical and displaced only along the c-axis, they willcoincide in this projection; therefore, each corner of the net-work of equilateral triangles represents both C and Si atoms.

All silicon-carbide types being built of layers of close-packed spheres will have trigonal symmetry by simple rotation about the c-axis. Each layer has $2-3$ and 6 fold symmetry axes normal to its plane. When two or more layers are put over one another, the 2-fold axes do not coincide with one another and, therefore, vanish. The 6-fold axes cancides with the 3 -fold axes, so that the resultant structure has only 3 -fold symmetry. The symmetry elements are shown in fig. (12a).

Now if in these close-packed layers we represent the silicon atoms by Roman letters and carbon atoms by corresponding Greek letters, the layers may ${ }_{\alpha}$ called $A \alpha, B \beta, C \gamma$ layers.

The different carborundum types will be built of such layers $A \alpha, B \beta, C \gamma$ of which no two successive layers are identical. In future for brevity these may be called $A, B$ and C layers, remembering that the corresponding Greek letter is implied in the case of silicon-carbide crystals.
4.6. REPRESENTATION OF THE POLYYYPES IN THE CIASSICAL ABC NOTATION

It is possible to represent the different polytypes by specifying the successive layers comprising the unit cell, in terms of the $A, B, C$ notation. The representation of some of the different polytypes is given in table(III).

Table III

| Crystal modification |  | CLASSICAL ABC notation |
| :---: | :---: | :---: |
| Old notation | Ramsdell's notation |  |
| I | 15 R | ABCACBCABACABCB |
| II | 6H | ABCACB |
| III | 4 H | $A B C B$ |
| VI | 33 R | ABCACBABCACBCABACBCABACABCBACABCB |

In a similar way all the different polytypes consisting of larger number of layers can also be represented. It will be noted that this representation becomes more and more unwieldy with the increasing number of layers and also does
not directly reveal the relationship between successive layers.

### 4.7. STACKING OPERATORS, ZHDANOV SYMBOL AND FRANK'S NOTATION

The arrangement of the successive layers is best represented in terms of the relationship between two layers or in terms of the "stacking operators". Though all the layers are equivalent to each other, they are displaced or rotated through $60^{\circ}$ with respect to each other. The pairs $A B$ and $B A$ are to be differentiated from one another. In the case of silicon-carbide crystals these layers are $A \propto B \beta$ and $B \beta A \alpha$, but as mentioned before for brevity only Roman letters may be used, the Greek letter being implied. The difference between $A B$ and $B A$ is best seen from figure (12b). If the layer $B$ is on top of $A$, each atom of $B$ (represented by $x$ ) lies at the centre of an equilateral triangle formed of the three atoms of $A$ (represented by o), such that wi th the suitable rotation of the figure, as in the figure drawn, these triangles are oriented as $\Delta$ i.e. the centre of the three spheres that provide a dimple, into which the sphere of layer $B$ fits, form an equilatral triangle which is oriented as $\Delta$. If, on the other hand, the layer A lies on top of $B$, the atoms of A lie at the centres of the equilateral triangles formed of the atoms of the layer $B$, such that these equilateral triangles are oriented as $\nabla$. Thus the relationship itself
between the layers may be represented as $\Delta$ and $\nabla$ respectively. It can at once be seen that when $C$ follows $B$ and $A$ follows $C$, the relationship is again $\Delta$ i.e. if $A, B$ and C layers follow each other in this cyclic order, the relationship between the layers is always $\Delta$. However, the other three alternative arrangements i.e. A following B; $B$ following C; C following A, will be represented by $\nabla$. This representation has memonic value also since a rotation through $60^{\circ}$ converts the operation $\Delta$ into $\nabla$.

This notation used by Frank (1951a)will represent the various polytypes of silicon-carbide crystal as given in the table IV, and will, hereafter, be referred as Frank's notation.

Table IV

| $\begin{aligned} & \text { Crystal Modi- } \\ & \text { fication in } \\ & \text { Ransdell's } \\ & \text { notation } \end{aligned}$ | Frank's Notation |
| :---: | :---: |
| 15R | $(\Delta \Delta \Delta \nabla \nabla) \Delta \Delta \Delta \nabla \nabla \Delta \Delta \Delta \nabla \nabla$ |
| 6H | $(\Delta \Delta \Delta \nabla \nabla \nabla) \Delta \Delta \Delta \nabla \nabla \nabla \ldots$ |
| 4H | $(\Delta \Delta \nabla \nabla) \Delta \Delta \nabla \nabla \cdots$ |
| 33R | $(\Delta \Delta \Delta \nabla \nabla \nabla \Delta \Delta \Delta \nabla \nabla) \Delta \Delta \Delta \nabla \nabla \nabla \Delta \Delta \Delta \nabla \nabla \ldots$ |
| $51 R$ | $(\Delta \Delta \Delta \nabla \nabla \nabla \Delta \Delta \Delta \nabla \nabla \nabla \Delta \Delta \Delta \nabla \nabla) \Delta \Delta \Delta \nabla \nabla \nabla \ldots$ |

Thus it will be seen that, for the hexagonal types, the number of $\Delta$ and $\nabla$ necessary to repeat itself is the 40.
same as the number of layers in the unit cell. In the rhombohedral types referred to the hexagonal unit, the number of layers within the unit cell is 3 times the number of $\Delta$ and $\nabla$ operators. The $\Delta$ and $\nabla$ repeat unit is enclosed within round brackets. This fact will be further brought out by the interferometric study (see Chapter 10).

This notation can be further contracted in the Zhdanov symbol (Zhdanov 1945) which consists of pairs of numbers in which the first is the number of consecutive $\Delta s$ and the second the number of consecutive $\nabla \mathrm{s}$ following the
$\Delta s$. Thus silicon-carbide of type $15 R$ would be represented by the symbol (32) and the commonest variety of silicon-carbide type 6 H by the symbol (33). The various polytypes of siliconcarbide are represented in Zhdanov's symbol in the table $V$. Table V

| Crystal inodi- <br> fication in <br> Ramsdells <br> notation. | Zhdanov's Symbol |  |
| :--- | :--- | :---: |
| 15 R | $(32)$ |  |
| 6 H | $(33)$ |  |
| 4 H | $(22)$ |  |
| 33 R | $(3332)$ |  |
| 51 R | $(33$ |  |
| 69 R | $(3333$ |  |
| 87 R | $(3333$ |  |

Ramsdell (1947) in his notation has given these numbers a slightly different significance and calls it the
"zig-zag sequence", which represents the sequence of succeeding atoms in the ( $11 \overline{2} 0$ ) section. Fig. (13) shows one such section. If a Si (or C) atom lies on A in one layer, in the next layer the atom may lie either to the right on $B$ or to the left on C. Say it lies to the right. Then the third layer may have its atom continued to the right or it may change direction and lie to the left. Thus the positions of atoms in the succeeding planes when joined together will.give a zig-zag pattern in the ( $11 \overline{2} 0$ ) section. Such an arrangement can be described in terms of the number of layers added in each direction in succession and is called by Ramsdell "zigzag sequence". Thus silicon-carbide crystals of types 15 R , 6H etc., will be represented by (32 32 32) and (33) etc., respectively. It may again be pointed out that in rhombohedral types, the symbol is always repeated three times. This is done to complete the unit cell such that the last layer lies directly above the initial layer. In the table II which gives the unit cell constants of the different polytypes, it may be noted that this correlates with $a_{r h}=\frac{1}{3}$ of the lattice parameter c .

Ramsdell pointed out that the various polytypes belong to the (3....2) series and predicted the type 69R, with the zig-zag sequence $\left(\begin{array}{lll}33 & 33 & 33\end{array} 3^{2}\right)_{3}$ and also other hexagonal structures like $10 \mathrm{H}, 16 \mathrm{H}$ etc. He also noted that the numbers in the zig-zag sequence are either 2, 3, or 4 , and that the
number 1 does not occur in these structures. He further made an important generalization that not only is the (33) structure of type 6 H the commonest of all modifications, it also occurs within most of other structures.

### 4.8. NOTATION USED BY JAGODZINSKI

Some other workers notably Jagodzinski (1949) have used a slightly different notation. In this notation consideration is taken not only of pairs of layers but of one layer on either side of a single layer. Any layer which is preceded and succeeded by the same type of layer is denoted by 'h' but if the two are different, the layer is denoted by 'k'. Thus the layer $B$ in the arrangement $A B A$ or $C B C$ will be denoted by ' $h$ ' and in the arrangement CBA or $A B C$, it will be denoted by ' $k$ '. Identical ' $h$ " and " $k$ " notations can be used for $A$ and $C$ layers. According to this notation silicon-carbide crystal of type 15R will be ( hk k h k ) and type 6H will be ( $\mathrm{hk} k$ ). Jagodzinski, further developed the general equations for the interaction between neighbouring layers in the arrangement and showed that the most probable layer type consisting of more than six layers of close-packed atoms is the siliconcarbide type with 15vlayers. This is the second commonest variety of silicon-carbide crystals.

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\text { Part } 111
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EXPERIMENTAL METHODS USED IN THE PRESENT STUDY

## CHAPTER V

## MICROSCOPIC TECHNIQUES

In the present investigation the experimental work may be divided into two parts. Firstly, the observation of growth spirals and other molecular features and secondly the measurement of step-heights. Therefore, two distinctly different techniques were employed for their study. Various microscopic techniques were utilized for the observation of these features; and for the measurement of step heights multiple beam interferometric techniques were used.

In both the microscopic and interferometric studies the silvering technique is needed; both the crystal surface and the optical flat used for interferometric studies have to be coated with a highly reflecting layer of silver. The silvering of the crystal surface is necessary for two purposes. Firstly, for the microscopic observation and secondly for the interferometric study when it forms the second (or the back) surface of the interferometer. The silvered optical flat forms the front or the first surface of the interferometer in the reflected system, and, therefore, it is essential, in order to secure good visibility of the fringes that it should have a low absorption. To achieve this, a silvering technique was used, as described below (see Strong (1940) and Tolansky (1946, 1948) ).

### 5.1. THE SILVERING TECHNIQUE

A commercial evaporating unit, built by Edwards and Co., of type $E_{3}$ was used for this purpose. This consists of a large vacuum chamber in the form of a glass bell jar 60 cm high and 40 cm . in diameter. This can be evacuated by a three staye silicon-oil diffusion pump backed by a rotary oil pump. The backing vacuum and final vacuum can both be read directly by the Pirani gauge and Phillips ionisation gauge supplied in the unit.

The surfaces of specimens must be thoroughly cleaned before silvering. The glass optical flat after being cleaned with soap water is cleaned with hydrogen peroxide ( $\mathrm{H}_{2} \mathrm{O}_{2}$ ) and distilled water, and then rubbed with clean dry cotton wool until no breath figures are obtained by lightly breathing on it. For the cleaning of silicon-carbide crystals, which are very resistant to chemical action, it was possible to use acids and other reagents e.g. nitric acid. Before the evaporation of silver, a final cleaning of the surfaces is performed inside the evaporation chamber by ionic bombardment from a high voltage discharge passed at a pressure of 1 mm . of mercury and lower. After this discharge cleaning spectroscopically pure silver is thermally evaporated from a molybdenum strip on to the specimens at as low a pressure as possible (ūsually $1 \times 10^{-5} \mathrm{~cm}$. of Hg ), so that a highly reflecting layer of silver with a low absorption is obtained.

Under these conditions the silver layer contours the
surface very closely without imposing any structure of its own. Electron-microscopio studies show that the distance of migration of silver atoms on the substrate, when deposited under these conditions is not more than 500 A (Picard and Duffendack 1943) and for high rates of evaporwtion, the mean distance of migration may be considerably reduced and it may be assumed that this will result in better contouring of the surface. (Ievinstein 1949). The usual rate of evaporation was such tha $t 90 \%$ reflectivity could be achieved in less than 10 seconds. In this evaporating unit the filament and specimen distance is quite large (nearly 50 cm ), so that any variation in density over the optical flat (diameter 2.5 cm ) or over crystal specimens (usually less than 5 mm . in size) is negligible; in fact it can be calculated to be less than $1 \%$ over a circle of 10 cm . diameter.

### 5.2. TECHIVIQUES OF OBSERVATION

The elementary growth features on silicon-carbide crystals are only faintly visible because of the small step heights $(e . g$. for type 6 H , the step height is 15 A ). Various optical techniques were tried for the observation of these features.
(a) Off-Focus Bright-Field Narrow Pencil Illumination.

Since the crystals are opague, they had to be studied in reflection. This has the additional advantage that for a step of height $t$, this increases the path difference
between the rays to $2 t$.

The clean surface of the crystal, when examined by a metallurgical microscope, using bright-field illumination, does not show up any of the molecular growth features, the surface appearing smooth. Therefore, the technique which was utilized by Griffin (1950) for the observation of growth features on beryl crystals was next tried. This consists first in depositing a thin, highly reflecting layer of silver, by the technique described in the previous section. The surface is then examined in reflection with a metallurgical microscope using bright field illumination, with the field iris stopped down to give a narrow illuminating beam. By slightly going off-focus, a phase difference is introduced between the diffracted wavefronts, which produces an intensity distribution, revealing much detail on the crystal surface. Even this method was not successful for the observation of the very elementary growth spirals.
(b) By Smearing Impurity on the Crystal Surface

It was soon discovered that a small amount of impurity can make these features visible. Fig (30) is an example where by suitably wiping the impurity on to the crystal surface (without silvering it) the faint spiral features have been made quite visible. This behaviour is easily understood since particles of impurity will pile up at the edges thereby increasing the visiolity. This method, though it was often
found helpful is not very satisfactory.
(c) Breathing Technique

This method considts in observing the clean surface of the crystal by a metallurgical type of microscope and focussing it sharply on the crystal surface. Breathing lightly on the crystal surface while it is under observation increases the visibility and the "lines" flash out because of condensation of water vapour but soon disappear when water evaporates. The 'lines' so observed have a dotted and diffuse appearance, but the visibility achieved is quite high. This method though very convenient and handy for visual observations is not quite suitable for photography. However, the utility of this technique for a preliminary survey of a large number of crystals in the search for the suitable crystals to be studied, is to be emphasized.
(d) Phase-Contrast Microscopy

The technique found most satisfactory for the observation of the growth spirals consisted first in depositing a highly reflecting (about $90 \%$ ) layer of silver on the crystal and examining it in reflection using phase-contrast illumination.

The principles of phase-contrast microscopy were first given by Zernicke (1934, 1935) and it is now a well established technique. No attempt will be made to give a detailed mathematical account of the theory. The theory andpractice
of phase-contrast microscopy has been discussed by several workers. (Burch and Stock 1942; Kohler and Loos 1941; Payne 1947; Taylor 1947, 1949). An excellent account of the principles and applications of this technique with an exhaustive bibliography is given by Bennett, Jupnik, Osterburg and Richards (1951). An elementary qualitative explanation of this technique is given below.

For the sake of simplicity, the object specimen will be considered as a single particle. This elementary theory can be extended to object fields of more than one particle, when the particles are far enough apart with relation to the resolving power of the objective so that the images of the various particles are formed independently of one another. It will be assumed that the microscope is adjusted for Kohler illumination i.e. the source of light is focussed upon the iris diaphragm of the substage condenser so that the opening of the condenser diaphragm may be regarded as a source of illumination. Further in discussing the image formation by the objective of the microscope, we shall consider the light wave radia ted by a single point of the condenser diaphragm, and it may be assumed that to a first order of approximation the main effect of including the light from the remaining parts is simply to produce a brighter image of the specimen.

If, the condenser diaphragm is placed near the first focal plane of the substage condenser, the light wave radiated from a point in the opening of the iris (in fig. (I) a) it is
shown to be on the axis of the condenser lens for the sake of simplification), emerges from the substage condenser as a substantially plane wave and, therefore, parallel rays pass through the object specimen. If the object specimen is an ideally simple one for phase contrast microscopy it may be taken as a single transparent particle embedded in a homogeneous medium of nearly the same index of refraction. Consider a light wave incident upon the specimen and its surrounding medium. The light transmitted by the surrounding medium and the particle will have the same amplitude because of equal absorption but will differ in the optical paths traversed i.e. there will be a slight difference in phase. Therefore, the light transmitted by the surrounding medium and the particle may be represented by the two equal vectors $S$ and $P$ respe ctively (fig. I4 b), such that $P$ is rotated with respect to $S$ by a small angle $\phi$ corresponding to the path difference. The vector $P$ can be resolved into a component parallel and equal to $S$, and a small component $D$ which will be nearly at $\pi / 2$ to the vector $S$ if $\phi$ is small Therefore, the incident wave does not pass without interruption through the object plane but may be sesolved into two parts (I) the $S$ part which is the undeviated wave by the presence of the object and (2) the remaining part $D$, which may be regarded as the deviated wave created by the light $S$ in its passage through the object. The deviated wave $D$ is zero at all points of the object plane except where there
is the object detail and will be diffracted as a set of roughly spherical waves expanding from the individual detail etc. These are drawn diagr ammatically in fig. (I) a) where the undeviated part is drawn by the solid line and the deviated part by the broken line. The undeviated wave continues on its original course as a set of parallel rays and is focussed in the second focal pla ne of the objective where the geometrical image of the souxce of light is formed and is subsequently spread uniformly over the image plane. The deviated wave originating from the object details is spread over the second focal plane of the objective and is subsequently focussed in the focal plane of the eyepiece. This important distinction bedween the deviated and the undeviated wave is the basis of phase-contrast microscopy.

The above analysis shows that the image of the surrounding medium is illuminated by the undeviated wave and therefore the amplitude and phase of light illuminating this region will be determined by the vector $S$ whereas the image of the particle is formed by both the undeviated and deviated waves and since these two waves overlap upon the geometrical image of the particle, they interfere with one another to give the resultant vector $P$ which will determine the phase and amplitude of the light which forms the image of the particle. This conclusion is true irrespective of the path difference between the particle and the surrounding medium.

Here it has been assumed that no light is diffracted outside
the objective.

Since the amplitudes of both $S$ and $P$ waves are the same, their vectors differing only in phase, the eye will not detect the specimen, since it does not detect any changes in phase, being sensitive only to intensity and colour changes. Therefore, an ordinary microscope will fail to reveal the presence of the specimen. If, however, the phase of either the undeviated wave $S$ or the deviated wave $D$ is changed by $\pi / 2$, the $S$ and $D$ waves will be either in phase or out of phase by $\pi$ and therefore the image of the particle will then be illuminated by light of amplitude $|S| \pm|D|$ and will be either brighter or darker than the background, the intensity of which is determined only by the vector $|S|$. This is exactly what the phase contrast microscope does. When regions of greater retardation are imaged darker than the background it is called the positive phase contrast and when brighter than the background it is called a negative phase contrast. At the back focal plane of the objective, where the geometrical image of the condenser diaphagm is formed, a 'phase-plate' is placed which consists of a dielectric layer of optical thickness $\lambda / 4$. The undeviated wave is focussed at the back focal plane forming the image of the condenser diaphragm, and if the phase plate exactly covers this area, the undeviated wave on passing through it will be changed in phase by $\pi / 2$.

Generally the deviated wave $D$ is much weaker than the
direct light $S$, in order to obtain optimum contrast the amplitudes of the two should be made nearly equal. Since we cannot increase $D$ without also increasing $S$ proportionately, we have the only alternative of decreasing the intensity of the direct light $S$. This decrease is accomplished by placing on the phase plate in the path of light $S$, some absorbing material, so that the amplitudes of the undeviated and deviated waves are arranged to give maximum contrast. It may be mentioned in passing that if the phase plate is opaque, the $S$ wave is completely obstructed, then the particle will appear with maximum contrast, but in practice the image is not suitable for the usual purposes of microscopy on account of the loss of definition in the image. This may be accounted for, since it is the deviated wave alone that forms the image and it will reveal the edges rather than the surface details. This, in principle, is the working of dark ground illumination.

Description of the Apparatus Used

The apparatus used was the Cooke Troughton \& Simms phase contrast equipment for incident illumination. This equipment can be fitted on the Vicker's projection microscope.

A diagrammatic scheme of the arrangement is shown in fig. (1) c). An annular diaphragm $D$ serves as the entrance pupil of the optical system consisting of a field lens, the microscope objective, and the reflecting surface of the
specimen (Si-C crystal). The light source is imaged on the diaphragm $D$ by the condenser lens. The field lens and the objective form an image $D_{1}$ of the field stop on the specularly reflecting surface of the object specimen. The light is reflected from the surface of the specimen and passed through the objective again to form a real image $D_{2}$ of the diaphragm D. Image $D_{2}$ becomes the exit pupil and therefore the location of the phase plate.

In this equipment, the optical assembly, the microscopic objective lenses, the beam splitter and the phase plate are mounted on the objective. The phase plate is located between the beam splitter and the eyepiece (shown by solid lines in fig. I4c) since in this position both the amount of stray light and losses of illumination are minimized. It is a positive phase contrast, with a single phase plate having $80 \%$ absorption with a phase retardation of $\pi / 2$ and it is found that this single phase plate serves moderately well for the entire practical range of small optical path differences.

The surface of the crystal specimen must be adjusted perpendicular to the optical axis of the microscope so that the image of the diaphragm is centred upon the optical axis when the condenser diaphragm has been centred. An auxiliary microscope is provided, which can be inserted in place of the normal eyepiece. This enables the examination of the back
focal plane of the objectives so that the image of the diaphragm can be made to coincide exactly with the phase plate.

The ring form of the substage annulus together wi th an annular phase plate has a considerable advantage. Since this form has complete axial symmetry, it introduces practically no undesirable lack of symmetry in the image, and the resolution is improved and depth of focus diminished due to the use of a larger objective aperture by direct light. Furthermore, less diffracted light is wasted owing to overlapping between the higher order spectra and the retarding annulus of the phase plate.

## (e) On the Visibility

- Phase-contrast microscopy depends upon altering phase changes into amplitude changes, conversely it changes real opacity into apparent changes of phase and for such features this technique is not suitable. Again, phase contrast microscopy is based on the physical possionity of complete or partial separation of the deviated and undeviated spectral orders at the phase plate. For coarser detail it may not be possible to isolate the diffraction effects from the direct light on account of small separation between the zero and higher order spectral images. Further the surface of the specimen should be in one plane and specularly reflecting in order to form a sharp image of the annular condenser diaphragm on the phase plate. If the different parts of the surface of
the specimen form different images of the diaphragm, as happens when small areas of the specimen though highly reflecting are inclined to each other, the advantage of the phase contrast technique is lost. In the limiting case, when the surface of the specimen diffuses light completely, no image of the annular diaphragm can be formed after the light passes through the objective the second time and the phase contrast can not be used at all.

Silicon-carbide crystals are ideal for this purpose. The faces are molecularly flat, the step-heights between the successive arms of the spiral being only a few angstrom units. The light from the surface is specularly and coherently reflected. There are no prominences or protuberances on the surface to scatter light to give unwanted background intensity: it is only the diffraction at the edges of the spiral steps that is solely responsible for the deviated wave and since all the steps in a particular growth spiral are of the same height and often with equal spacing between the successive steps, the diffraction effect will be occurring in an ideally symmetrical way. Further, by silvering the crystal so that the surface has a high reflection coeffieient, phase plates with quite a high absorption can be employed to give a correspondingly high contrast in the image, and the time of exposure is considerably shortened, thereby cutting down the stray background intensity. Even then it is rather surprising
that such small steps as 15 A , which will correspond to a change in path of 30 A in reflection, have been revealed. However, with the equipment used these features are often still faint and only just visible. In order to make these features reproduceable, photographic methods for increasing the contrast have been employed. (See next section).

In phase-contrast microscopy the best contrast is obtained when the specimen is exactly in focus. This is in contrast to bright-field microscopy where defocussing is used to see specimens of low contrast (Iinfoot 1945). If the inhomogeneties on the surface of the specimen are not confined approximately to a thin lamina, in putting the specimen out of focus to see these details, the image will bear no simple correspondence to the object itself. On the other hand, in phase contrast microscopy the maximum contrast is obtained when the specimen is accurately in focus so that the image bears a closer resemblance to the object; the phase contrast image is symmetrically diffused above and below the focus. Furthermore, the phase contrast microscope is operated at full aperture and it is unnecessary to close the condenser diaphragm partially as in the case of the bright-field microscope, in order to obtain enough edge diffraction to see such a specimen. Therefore, in phase contrast microscopy there is practically no decrease in resolution and spurious images are less likely to occur.

In fig. (82) it is seen that the visibility and contrast is much greater than that of fig. (81) which shows
the photograph, using phase contrast equipment, of the same part of the crystal after silvering. In fig. (82) the surface of the crystal was not very clean when it was silvered. The silver deposit was not uniform, the surface appearing mottled. Examination with the same phase-contrast equipment gave this surprisingly high visibility. This suggests that impurity can make the steps more visible.

## (f) Photographic Processing

The photographic processing consists of the following series of operations. Firstly, very contrasty photographic plates such as Kodak B-20 Process plates were used, the exposure time being critically controlled to bring out the edges of the spiral steps prominently. These plates were then developed in a contrasty developer such as Kodak D-8 caustic developer. In some cases, especially if the step height was comparatively large, this photographic processing provided a negative of sufficient contrast, and further contrast was obtained in printing, by using extra-hard photographic paper. In some cases these negatives did not have sufficient contrast and by printing them against another contrasty photographic plate and again adjusting the time of exposure critically, the contrast was considerably increased - indeed any amount of contrast can be achieved by working at the heel portion of the exposure - density curve of the photographic plate, the only disadvantage being that contrast at unwanted places of
the negative also increases. Unless otherwise stated, all the pictures have been taken by the use of the above phasecontrast microscope.

## HEIGHT

### 6.1. GENERAI

For the measurement of step height, multiple-beam interferometric techniques were used. Since multiple-beam interferometry is quite a well established technique, no attempt will be made to give a general treatment of the theory, a full account of which has been given by Tolansky (1948). Only those points which have a special bearing on the present investigation, and some new modifications introduced for these studies will be indicated.

The crystals of silicon-carbide are opaque, therefore, interference fringes in the reflected system were always utilized. The theory of the reflected system has been discussed by Hamy (1906) and Holden (1949). The fringes are produced by matching the crystal surface on which a thin layer of silver (about 300 A thick and $90 \%$ reflectivity) has been deposited, against a similarly silvered optically polished glass flat. The optical flat used was supplied by Adam Hilger and was true to $\lambda / 40(\lambda 5461)$ over the eentral area of nearly 1 cm . diameter, but was certainly flat to a much smaller fraction of this over small areas.

In an interferometer of which the two component surfaces are parallel to each other separated by a distance t ana
silvered such that the transmission and reflection coefficients of amplitude are $T^{\frac{1}{2}}$ and $R^{\frac{1}{2}} r e s p e c t i v e l y$, the transmitted series of multiple reflected beams when summed up gives the well known Airy intensity distribution

$$
I=\frac{T^{2}}{(1-R)^{2}} \cdot \frac{1}{1+\frac{4 R}{(1-R)^{2}} \sin ^{2} \delta / 2} \cdots \cdots-\cdots(18)
$$

where $\delta=\frac{2 \pi}{\lambda} \cdot 2 \mu t \cos \phi$, is the constant phase lag between the successive beams, $\phi$ being the angle formed by the normal and the ray between the silvered surfaces.

The properties of the reflected system in multiple beam interference ane much more complicated. The peculiar properties of the reflected system are due to the fact tha $t$ the first reflected beam has a phase change compared with the second beam altogether different from that between any other two successive beams. It is found that for highly reflecting silver films $(\mathrm{R}>80 \%)$, the intensity distribution in the reflected interference system is very nearly complementary to that in the transmitted system forming narrow symmetrical minima.

In order that sharp interference fringes should be produced for two highly reflecting surfaces inclined at a small angle, Airy summation should apply. But in this case the path difference between the successive reflected beams
is not constant but alters progressively with the order of reflection so that the beams gradually get out of step ultimately, the retardation becoming $\lambda / 2$ tending to destroy the condition for the formation of sharp fringes. The path difference between the first and the $n^{t h}$ beam is $2 n t-\frac{4}{3} n^{3} \theta^{2} t$ where $\theta$ is the wedge angle. Hence the second term $\frac{4}{3} n^{3} \theta^{2} t \quad$ should be restricted to a maximum value of $\lambda / 2$. Therefore, $t$ should be as small as possible and must in any case be less than the critical value.

For the study of the topography of the crystal surface it was always found advantageous to utilize high dispersion fringes which are produced by having a very small wedge angle between the crystal surface and the optical flat. Further, in accordance with the previous result the separation between the two surfaces was reduced to as small a value as possible normally only 2 or 3 wave lengths of light. This could be achieved because the small portions of the surfaces of siliconcarbide crystals studied, are exceptionally flat without any ridges or protuberances, so that the two surfaces could be brought in very close contact. The experimental technique for achieving this is simple. A brass jig was used in which the optical flat fits in a groove at the base and the crystal specimen fixed on to another grass plate can be brought close to it at any inclination by adjusting the three nuts which press against three springs separating the two brass plates.

Under these conditions extremely sharp multiple-beam interference fringes were obtained, actually a fringe width $\sim \frac{1}{50}$ of an order separation were easily achieved. It may be emphasized that since the interference gap was adjusted to be very small the multiply reflected beams effectively scan the same part of the crystal surface and thereby reveal the true topography.

In the present study the two types of interference fringes used are, firstly Fizeau fringes of equal optical path formed, by illuminating the interferometer with a parallel beam of monochromatic light $(\lambda 5461)$. The experimental arrangement for the production of Fizeau fringes in the reflected system is shown diagrammatically in fig. (15). Secondly the fringes of equal chromatic order formed with white light using a spectrograph, were utilized. These fringes were obtained by placing the spectrograph such that its slit occupies the position previously occupied by the photographic plate in the arrangement for Fizeau fringes.

### 6.2. USE OF FIZEAU FRINGES

When the step height is comparatively large ( $\sim 100 \mathrm{~A}$ ) it was found possible to determine the individual step heights by the shift of Fizeau fringes at these steps. The shift of the Fizeau fringe at a step, as a fraction of the order separation (i.e. the distance between successive fringes), gives
the height of the step as a fraction of $\lambda / 2$. An example of this method of the determination of step height is shown in fig. (16a) which shows Fizeau fringes passing over the spiral steps of fig. (16b). It is seen in fig. (16a) that the dispersion is not constant and therefore for the evaluation of the step height an average value was taken.

However, in most of the features the individual steps are rather close to each other and the step heights too small to be detected by the individual shift of Fizeau fringes at these steps. The two simple cases of growth spirals in which the average step height can be determined are (a) circular spirals and (b) polygonal spirals with straight edges, having a regular spacing between the successive arms of the spiral. The relevant formulae for the determination of the average step height of these simple cases are developed below.
(a) Rounded Spirals

A rounded spiral is effectively a spiral conical hill. In the simple cases as illustrated in figs. (21) and (35) etc., it may be considered to be a conical hill made of a series of concentric steps with a constant spacing $d$ and a step height $h$ (fig. 17a). A Fizeau fringe in the direction $A B$ will be shifted by an amount $s=E P$ when it climbs each step, and will be broken into small parallel portions CD, EF, GH .... The apparent direction of the fringe will be CEG..... 0 , since these
portions are small. For the special case when the fringe passes over the peak, the apparent direction of the fringe will be radial and hence perpendicular to the steps. A symmetrical shift will occur in the opposite direction down the hill from 0 in the direction $O L$. If $\theta$ is the angle between the true and apparent direction of the fringe, the fringe will bend through an angle $2 \theta$ at the peak. From the figure

$$
s=d \cdot \sin \theta \quad-------(19)
$$

By knowing the dispersion $X$, the distance between successive fringes which corresponds to a difference of $\lambda / 2$ in the width of the interference gap, the step height $h$ corresponding to fringe shift $s$ is given by:

$$
\begin{aligned}
h & =\frac{s}{x} \cdot \frac{\lambda}{2} \\
& =\frac{d \cdot \sin \theta}{x} \cdot \frac{\lambda}{2}
\end{aligned}
$$

$$
-------(20)
$$

The optical flat is adjusted such that high dispersion fringes are obtained with one of the finges passing over the peak where it will be observed to bend. This adjustment is very delicate especially using high dispersion fringes.

From this Fizeau picture $\theta$ is measured, and knowing d from a microphotograph at the same magnification, $h$ is found.

Here the spiral conical hill has been regarded as a circular conical hill which is very nearly true. Fig. (l8a) illustrates an example of this method which shows a Fizeau fringe ( $\lambda$ 5461) passing over the spiral of fig. (18b).

Since the step height is obtained from the mean of all those contributing to form the peak, irregularities of the optical flat and the lack in faithfulness of silver contouring are averaged out. This method is, therefore, capable of considerable accuracy.
(b) Polygonal Spirals with Straight Edges

In this analogous case the pyramidal hill may be regarded to be composed of series of parallel steps on each side of the vertex. For a series of parallel steps of step height $h$ and separation $d$ the Fizeau fringes will have an apparent direction at an angle $\theta$ to the real direction. In the particular case when the Fizeau fringe has been adjusted to run perpendicular to the series of steps on one side of the vertex, the apparent direction of the Fizeau fringe will be inclined at an angle $\theta_{3}$ on one side of the vertex and $\theta_{2}$ on the other side, to the true direction of the fringe. $\theta_{I}$ and $\theta_{2}$ from fig. (17b) are given by the relations

$$
\begin{align*}
& \sin \theta_{1}=\frac{s}{d}  \tag{21}\\
& \sin \theta_{2}=\frac{s}{d} \cdot \cos \left(\theta_{1}+\theta_{2}\right) \tag{22}
\end{align*}
$$

and putting

$$
\begin{equation*}
\theta_{1}+\theta_{2}=2 \theta \tag{23}
\end{equation*}
$$

From these three equations $\theta_{1}$ and $\theta_{2}$ may be eliminated in terms of $\theta$, s and $d$, giving

$$
\begin{equation*}
\frac{s}{d}=\frac{\sin 2 \theta}{\sqrt{1+3 \cos ^{2} 2 \theta}} \tag{24}
\end{equation*}
$$

Using the relation

$$
\begin{equation*}
h=\frac{s}{x}, \frac{\lambda}{2} \tag{25}
\end{equation*}
$$

the step height $h$ is given by

$$
\begin{equation*}
h=\frac{d \cdot \sin 2 \theta}{\sqrt{1+3 \cos ^{2} 2 \theta}} \cdot \frac{1}{X} \cdot \frac{\lambda}{2} \tag{26}
\end{equation*}
$$

Here $2 \theta$ is the total angle through which the fringe appears to bend at the vertex. When $2 \theta$ is small, as is usually the case for small step heights equation (26) reduces to

$$
\begin{align*}
h & =\frac{d \cdot \sin 2 \theta}{2} \cdot \frac{1}{x} \cdot \frac{\lambda}{2}  \tag{27}\\
& \doteq \frac{d \sin \theta}{x} \cdot \frac{\lambda}{2} \tag{28}
\end{align*}
$$

which is identical with the equation (20) used for circular

$$
67 .
$$

spirals. Fig. (19b) illustrates an example of this which shows the Fizeau fringes passing over the spiral of fig. (19a).

### 6.3. USE OF FRINGES OF EQUAL CHROMATIC ORDER

Application of fringes of equal chromatic order to the evaluation of step height is very much simplified in the special case of a Fizeau fringe passing over the centre of the spiral. The interferometer is adjusted so that the middle point of the length of the slit of the spectrograph passes over the peak of the conical hill, and is parallel to one arm of the Fizeau fringe. Then over one half of its length along the slit the interferometer will have a constant thickness till it reaches the peak after which the gap will increase depending upon the number of steps crossed by the slit. This will, therefore, lead to a system of fringes of equal chromatic order parallel to the spectrum lines in one half and sloping towards the red in the other. The increase in gap $\delta t$ is given by the relation

$$
2 \delta t=n \delta \lambda \ldots . . . . .(29)
$$

where $\delta \lambda$ is the corresponding change in wavelength is a particular fringe of order $n=\frac{\lambda^{\prime}}{\lambda-\lambda^{\prime}}$ where $\lambda^{\prime}$ is the wavelength of the neighbouring order ( $n+1$ ). From fig. (20)

$$
\delta t=2 N h \ldots \ldots-(30)
$$

where $\mathbb{N}$ is the total number of steps crossed by the slit,
and $h$ is the step height. Fig. (18c) illustrates an example of this method which shows the fringes of equal chromatic order corresponding to fig. (I8a). The spectrograph used in this figure was a Hilger constant deviation spectrograph with a dispersion of approximately 50A per m.m. near $\lambda 5461$. 6.4. BY COUNTING THE NUMBER OF STEPS ON EITHER SIDE OF A BOUNDARY IINE

In one case another determination of the step height has been possible. In fig. (18b) starting from the centre of the spiral we can reach any point $A$ on the line of discontinuity (running from left to right to the centre of the figure) either by going round the 'fish-like' obstruction in a clockwise or an anti-clockwise direction. In the former case, we encounter, say $\mathbb{N}_{1}$ steps. Therefore, the point $A$ is $\mathbb{N}_{1}$ steps lower with respect to the centre of the spiral. In the latter case we go down say $N_{2}$ steps from the peak of the hill in order to arrive at $A$. Thus at $A$ the difference in level on the two sides of this line of discontinuity is that corresponding to $\left(N_{2}-N_{1}\right)$ step heights. This difference is quite large (over 50 steps) and is, therefore, capable of being measured accurately and easily, either by Fizeau fringes as shown in fig. (18d), or by fringes of equal chromatic order. Knowing this, the step height has been evaluated but it is subject to uncertainty due to the possible presence of hidden dislocations in the obstacle and in the line of discontinuity.

### 6.5. SUPER POSITION OF FIZEAU OVER THE MICROPHOTOGRAPH

In this method the microscopic picture and the corresponding Fizeau fringes passing over this feature are photographed separately as usual, and are then superimposed over one another photographically, at the same magnification. In this way the exact position of the Fizeau fringe, the corresponding separation between steps etc., are all known with certainty. This method is of particular use when the separation between the successive steps is not constant, in which case the Fizeau fringes will appear curved. For the evaluation of step heights in such cases, two straight portions of the Fizeau fringes pa ssing over the vertex of the growth hill can be chosen, one on either side of the vertex and the corresponding step separation 'd' can be substituted in equation (28). This will, consequently, lead to higher accuracy in the determination of step height. Fig. (19c) illustrates an example in which the Fizeau fringes fig. (19b) passing over the spiral of fig. (19a) have been superimposed on it.

### 6.6. EFFECT OF DIFFRACTION

In all these figures, the effect of diffraction at the steps can be observed and this becomes more noticeable for molecular steps with high dispersion fringes formed in a small interferometric gap. As seen in fig. (16a), a portion of the fringe runs along the edge of the step in both
directions on either side of the fringe and is of minimum extension when the fringe is perpendicular to the step. Fig. (l8e) is an illustration of the effect for the spiral of fig. (18b) under very high dispersion. This diffraction has been of considerable assistance since it makes the topographical features visible simultaneously with the interference fringe, so that it becomes possible to adjust the fringe direction and position exactly over a certain feature, e.g. the fringe can be made to pass exactly over the peak of the hill or it can be adjusted perpendicular to the edges of steps, or the exact number of steps crossed by the slit of the spectrograph in the case of fringes of equal chromatic order can be determined accurately.


#### Abstract

Part IV

OBSERVATIONS ON SILICON-CARBIDE CRYSTALS


(A) MICROSCOPIC STUDIES
(B) INTERFERONETRIC STUDIES

## (A) MICROSCOPIC STUDIES

## INIRODUCTION AND CLASSIFICATION OF SPIRAIS

Silicon-carbide crystals often have very well developed and molecularly flat surfaces over wide areas and hence are most suitable for the observation of the molecular growth features of the type predicted by Burton, Cabrera and Frank's theory. Previous observations on Si-C crystals have already been quoted.

Simultaneously with the author (Verma 1951), Amelinckx (1951) also observed spirals on silicon-carbide crystals. Amelinckx could show that the step heights of some spirals was up to 35 A and thought that some were probably unimolecular, but no exact measurements were reported. By comparison with Griffin's work on beryl, these spirals were inferred to be growth spirals. However, by the application of improved experimental techniques discussed in Part III, it was possible in the present investigation to study these features in greater detail, the results of which not only confirm many of the theoretical predictions but also provide new facts and data.

As has been seen in Part III, the experimental observation may be divided into two parts viz. the microscopic, which will be presented first and the interferometric.

On the (0001) faces or the basal planes of silicon-
carbide crystals numerous growth spirals have been observed. The different types of growth spirals observed can be divided into three types.
(1) The elementary type of spirals originating from a simple dislocation in which the step height is equal to the size of the X-ray unit cell.
(2) Spirals originating from dislocations of multiple strength in which the step height is a multiple of the size of the X-ray unit cell.
(3) Interlaced spirals in which the step height is a fraction of the size of the X-ray unit cell.

## EIEMENTARY SPIRALS

This first class of spirals are those in which the step height between the successive arms of the spiral is equal to the size of the X-ray unit cell. These spirals are usually faint to observe because of the small step-heights (e.g. for type 6 H , the step height is 15 A ) and are, therefore, seldom seen with the ordinary microscope. It is therefore unlikely if this type of spiral had been seen by previous workers.

### 7.1. SHAPE OF THE SPIRALS

(a) Circular Spirals

Taking the simplest case, when a single screw dislocation emerges on the face of the crystal, a molecular ledge will run from this point of emergence on the crystal surface to one of its boundaries. If now the supersaturation of the vapour in contact with the crystal is raised, growth will start when the supersaturation has been raised to such a value that the critical nucleus as defined by equation (16) can pass between the dislocation point and the crystal boundary. As seen in Chapter (II) the ledge will curl up and form a spiral. The exact shape of the spiral will depend upon the rate of advance of a growth front in different crystallographic directions. The simplest case will be that in wich the rate of growth is independent of the crystallographic orientations.

Such conditions are likely to occur in growth from vapour when the factor $\beta$ does not vary with orientation in the crystal face in the following equation (equation (11)) which gives the rate of advance of a 'straight' step

$$
v_{\infty}=2(\alpha-1) x_{s} Z \beta \ldots-\ldots \text { (II) }
$$

As seen from equations (2) \& (9) viz.

$$
\begin{align*}
& x_{0}=\frac{1}{2} a \exp (\phi / 2 k T) \cdots-\cdots \text { (2) } \\
& x_{\mathrm{s}}=a \exp (3 \phi / 2 k T)-\cdots \text { (9) } \tag{9}
\end{align*}
$$

under which circumstances the estimates of surface diffusion distance $x_{s}$ and mean distance $x_{0}$ between the kinks on the steps are such that $t x_{s} \gg x_{0}$ even for orientations of closest-packed directions. Thus when the distance between the "Frenkel-kinks" or exchange sites is small and the mean displacement of the adsorbed molecule is large, the molecules will. have a high probability of adhering to the step if adsorbed near it, irrespective of the orientation of the step. Therefore, the rate of ledge advance will be independent of the crystallographic orientation and a rounded spiral will result, the shape of which can be calculated under these assumptions, as given by Burton, Cabrera and Frank (1951).

We know that a ledge which forms a portion of the spiral and has a radius of curvature $\rho$, will advance with
a. velocity $v_{\rho}$ given by

$$
\begin{equation*}
v_{p}=v_{\infty}\left(1-\rho_{c} \mid P\right) \tag{13}
\end{equation*}
$$

provided the supersaturation is not too high. $\int_{c}$ is given by equation (16) viz.

$$
P_{c}=a \phi / 2 k T \ln \alpha \quad \ldots . .-(16)
$$

Let $\theta(r)$ represent the rotating spiral in (rotating) polar coordinates ( $r, \theta$ ). The radius of curvature at a point $r$ will be

$$
\begin{equation*}
\rho=\frac{\left(1+r^{2} \theta^{\prime^{2}}\right)^{3 / 2}}{2 \theta^{\prime}+r^{2} \theta^{\prime 3}+r \theta^{\prime \prime}} \tag{31}
\end{equation*}
$$

where $\theta^{\prime}$ and $\theta^{\prime \prime}$ are the derivatives of $\theta(r)$. If the angular velocity of the whole spiral is $\boldsymbol{\omega}$, the normal velocity at the point $r$ is

$$
v(r)=\omega r\left(1+r^{2} \theta^{\prime 2}\right)^{-\frac{1}{2}}
$$

$$
\ldots \ldots(32)
$$

These three equations give $\theta f r$ ) and $\boldsymbol{W}$. A good approximation is obtained by taking an Archimedean spiral

$$
\begin{equation*}
r=2 \rho_{c} \theta>0 \tag{33}
\end{equation*}
$$

which has the proper central curvature. $W$ is then given by

$$
\begin{equation*}
\omega=\frac{v_{\infty}}{2 \rho_{c}} \tag{34}
\end{equation*}
$$

A better approximation as calculated: by Burton, Cabrera and Frank is

$$
\begin{aligned}
\theta & =\frac{3^{\frac{1}{2}}}{2\left(1+3^{\frac{1}{2}}\right)}\left[r / p_{c}+\ln \left(1+r / 3^{\frac{1}{2}} p_{c}\right)\right] ; \\
\omega & =3^{\frac{1}{2}} v_{\infty} / 2 p_{c}\left(1+3^{\frac{1}{2}}\right) \\
& =0.63 v_{\infty} / 2 p_{c}
\end{aligned}
$$

The value of $\boldsymbol{\omega}$ obtained by equation (35) differs from equation (34) only by a factor close to 1 , showing that $\omega_{\text {is }}$ insensitive to the actual law of dependence of $v$ on $P$ in the range in which $\rho \sim P_{c}$.

The spacing between the successive arms of the spiral
will be constant and will be given by

$$
\delta r=4 \pi \rho_{c} \quad \cdots-\cdots--(36)
$$

Such circular spirals are illustrated in figs. (21) (33) (35) (36) etc. The spacing between the successive arms of the spiral is not constant and in nearly every case the spacing is close at the centre, increases gradually, finally becoming constant. This may be attributed to increasing supersaturation in the last phase of growth.
(b) Polygonal Spirals

Any dependence of the rate of advance of a growth front on its orientation would impose a distortion of the growth spirals. This will happen when the factor $\beta$ in the above quoted equation (ll) varies with orientation in the crystal face. An obvious source of variation is that in which the step is parallel to certain close-packed directions. The step will, then, have relatively few 'kinks', the kink energy being high. Thus the condition $x_{s} \gg x_{0}$ will no longer be true, so that when the kinks are few and far between and the distance moved by the adsorbed molecule is small, polygonal spirals will result, the edges of the steps becoming straight in directions at right angles to the directions of minimum growth. Between these two extreme cases, there will be a series of intermediate ones.

Thus for growth taking place under these conditions, when the growth spirals become polygonal, they will exhibit the symmetry of the crystal faces. When viewing spirals on the (0001) planes, the edges of the stacks of monolayers are being observed along the c-axis and will therefore exhibit symmetries corresponding to these monolayers. Each monolayer of $C$ or Si (and the following Si or $C$ ) by itself has hexagonal symmetry, but the two layers put together have only trigonal symmetry since the hexagonal axes of one coincide with the threefold axes of the other. A hexagonal symmetry can arise by virtue of a $\sigma_{3}$ screw axis.

Fig. (22) shows the extreme case of a hexagonal spiral observed on a crystal identified to be of type 6 H . This is a regular hexagonal spiral, showing clearly the dependence of the growth rate on the crystallographic orientation. The edges very near the centre show a curvature, which in accordance with the theory, decreases with the distance from the centre. Soon the straight step-lines start rounding off at the corners and become gradually curved on moving away from the centre. These step lines do not meet the line of discontinuity sharply, but tend to curve away fromit, as shown in fig. (22), for the outer five or six step lines.

Fig. (16b) shows a further example of a spiral with straight edges. This spiral has a high visibility under phase-contrast illumination. Calibration by multiple-beam interference fringes has shown the step height to be nearly 130A. Here the central 1 or 2 turne are nearly circular before it becomes hexagonal. In one corner four edges are displaced from the regular shape and the straight edges are observed to have 'kinks' at several places.

Figs. (25), (26) and (29) are further examples. In fig. (25) some 10 turns at the centre stand out from the remaining turns. They are very closely spaced as compared to the rest of the figure and have an almost constant spacing, their shape being nearly circular. It may be noted that the step lines have a dotted appearance which may be due to the
deposition of impurity or some local etching at the edges of steps. Figs. (26) and (29) are being commented upon later in Sec. (7.2).

Fig. (18b) shows a spiral observed on a silicon-carbide crystal of type 6 H . It is nearly circular at the centre and gradually takes on the hexagonal symmetry of the crystal face. This exemplifies the intermediate case where the conditions of growth are not preponderantly either in favour of a circular or a polygonal spiral. Figs. (23) and (24) are further examples of such a case.

The central part is circular in many of the polygonal spirals. Fig. (34) shows further example of this behaviour. This indicates that the growth of the central part, which represents the last phase of growth, took place under conditions such that circular spirals could be formed. It may be assumed that in the last phase of growth when the furnace was switched off, the supersaturation increased as the temperature decreased. The shape may be attributed to these two controlling factors. Thus in fig. (25), the supersaturation was high in the last phase of growth and it remei ned fairly constant over such a period that some 10 spiral turns closely spaced could be developed.

The reverse case of a circular spiral having a centre with straight edges forming apolygonal spiral, has not been observed.

### 7.2. PROPERTIES OF GROWTH FRONTS AND THE INTERACTION OF GROWTH SPIRAIS

In order to understand the more complex growth patterns observed on crystal faces where two or more screw dislocations emerge, a description of some of the general properties of growth fronts will be given.

The regular circular spiral shape produced by growth controlled by a single screw dislocation will, under constant conditions, rotate without changing its shape, which at least for fast rotation will appear as if circles are being emitted from the centre, travelling outwards at a constant speed. For polygonal spirals the straight portions are actually advancing radially and so a similarity to wave emitted from a point source does present itself.

The analogy, however useful in many cases, cannot be extended to interference between growth fronts from two sources, but the terminology will be adopted to a certain extent.

When the advancing growth fronts meet an obstruction, they can propagate round corners as shown at the upper end of the 'fish' like obstruction in fig. (18b). It might be said that this point behabes like a secondary source of growth fronts.

The growth fronts emitted by two sources do not interfere like ordinary wave fronts. Where the two edges meet,
they fuse and annihilate each other over the comon portion. Numerous examples of this can be seen in figs. (24), (33), (35), (46), (47) etc.

When there are several screw dislocations actively emitting growth fronts, a point on the crystal face will be in the dominant field of only one of these and this alone determines the number of growth fronts passing over it. This is illustrated in figs. (33), (35), (44) etc. By choosing the point of observation on the crystal face of fig. (4 4 ) which shows the growth fronts emitted by five screw dislocations and fixing it, say, near the bottom screw dislocation, the number of growth fronts passing over it is solely determined as if this alone were active.

Sometimes anongst the dislocations emerging on a crystal face, one may dominate the rest. This will happen if the supersaturation at one centre is slightiy greater than that at other centres. The growth pattern originating from these weaker sources will continually shrink and if conditions remain constant ultimately only one growth pyramid will be seen. This is illustrated in fig. (26) where the central screw dislocation is dominant and determines the rate of crystal growth of the face. The weaker screw dislocations play little part in growth, and merely pass on the growth fronts received from the dominant screw dislocation with a slight delay and in slightly modified form. This is clearly seen \fig. (26). Here
the central screw dislocation has developed some four turns before reaching the point where the second small screw dislocation emerges. They quickly accomodate each other and the growth fronts issuing from the central screw dislocation, as they travel past this dominated screw dislocation, are only slightly distorted from their regular shapes. However, in the last phase of growth, when the furnace is switched off, the growth fronts would stop arriving from the dominant centre, and the growth steps attached to the weaker screw dislocations would be able to develop one or two turns of their own, as seen in fig. (26). Near the edge of fig. (26), some more screw dislocations emerge on the face of the crystal. Fig. (27) shows this portion of fig. (26), and $i i_{g}$. (28) is an enlargement of this area. These new screw dislocations also yield within a short while to the domination of the central one and quickly fall in line; their behaviour also being the same as outlined before. A further example of such a behaviour is shown in fig. (29).

### 7.3. GROWTH PATTERN FOR TWO SCREW DISLOCATIONS

(a) Two Screw Dislocations of the Same Sign:

Phenomenon of co-operation

The growth pattern when two or more screw dislocations emerge on the face of the crystal can now be explained. Taking the next simplest case of two screw dislocations of the same hand closer together than $2 \pi \rho_{c}$ they will generate a pair of
non-intersecting growth spirals. In the lower half of fig. (30) this unique example is illustrated where the spiral is doubled with the members strictly "parallel". These two dislocations may be said to co-operate with one another and will behave like one dislocation of double strength.

With the increase of distance between the two dislocations, the ledges originating from one will intersect with the ledges starting from the other. In fig. (31) the growth pattern for two screw dislocations $A$ and $B$ of the same hand is drawn schematically for the simple case of circular spirals. The step-height and structure of the step wall originating from these two dislocations is assumed to be identical. (The more general case, where fault surfaces will be produced is discussed in Sec. 7.8). The ledge starting from A goes on rotating and generating the spiral until it meets at $p_{1}$ the ledge originating from $B$, where it terminates. According to the properties of growth fronts, the two ledges will fuse with one another at $p_{1}$. As the spirals unfold themselves the ledges meet at $p_{1}, p_{3}, p_{5}, \ldots-$ in the upper half, and at $p_{2}, p_{4}, p_{6}, \cdots-$ in the lower half of the figure. (The loci of points of intersection are treated in Sec. 7.6). Over the common portion, between $p_{1}$ and $p_{2}\left(p_{3}\right.$ and $\left.p_{4}\right)$ etc., the two ledges annihilate themselves and the missing parts of the two spirals are shown by the dotted line. The resultant figure is the solid line curve. Starting at the dislocation point $A$ and going round the spiral we descend by one step in

$$
84 .
$$

each complete turn until we come to the point $p_{1}$. From $p_{1}$ we go round the spiral $B$, to the point $p_{4}$, and then again on the spiral $A$ to the point $p_{5}$. Thus in going round the resultant curve once, we descend by two steps from $p_{1}$ to $p_{5}$ to $p_{9}$ and so on. Similarly starting from the dislocation point $B$ and going round we descend by two steps from $p_{2}$ to $p_{6}$ etc. As the curves gradually smooth out at the points of contact, the figure will appear to be two spirals alternately spaced.

Fig. (31) has been drawn for circular spirals, and the case for spirals with straight edges can similarly be drawn where the behaviour will be the same. Furthermore in fig. (31) the spiral attached to $A$ has been shown to have developed two turns and that attached to $B$ only hall a turn before the two meet each other. It is quite possible for either of them to make any number of turns (including less than one turn) before meeting. The following figures illustrate the different cases. Fig. (32) shows the case of two screw dislocations of the same sign where both spirals are circular and the separation between the two dislocation points is such that each spiral has developed nearly one turn before meeting the other. The compound growth pattern in accordance with the method outlined, has developed in this figure for some two or three turns after which the ledges from the neighbouring dislocations interact with one another.

With the increase of separation between the two
dislocation points the growth pattern will have a shape similar to that drawn in fig. (31) and illustrated by figs. (33) and (35).

It has been seen that a spiral may not be circular or polygonal throughout. The central turns of several polygonal spirals have been observed to be circular. The resultant growth pattern will be built up by a mechanism similar to that drawn in fig. (31), with the difference that after the central circular portions, the ledges of the spirals change into straight edges. This transition may be gradual or sudden. Fig. (34) shows the case of two similar screw dislocations close to one another so that growth starts from both of them. The spirals are circular at the centre for one or two turns after which they settle down as spirals with straight edges. The meeting of the growth fronts from the two dislocations results in small kinks in the innermost straight edges. As in the case of circular spirals, by going round the resultant figure, we descend by two steps in each turn and the figure has the appearance of two spirals alternately spaced. The step-height between successive lines in any particular direction remains one unit. The spiral of fig. (34) has been observed on a crystal of type 15R, the full spiral being shown in fig. (19a).
(b) Two Screw Dislocations of Opposite Sign

> When two screw dislocations of opposite sign emerge on the face of the crystal a ledge will run between them
(fig. (37)). Growth will start if the supersaturation is raised to such a value that the diameter of the critical nucleus ( $2 \rho_{c}$ ) is less than the distance between them. In the more general case when the critical nucleus is not circular, this will be equivalent to a correctly oriented critical nucleus passing between the two dislocation points. As long as the supersaturation is kept above this value, the adsorbed atoms will join the step and therefore the step tends to spiral around both dislocations. This is shown in Iig. (38) looking down from above. However, as the step doubles back on itself (fourth stage shown in fig. 38 a ), the two points $A$ and $B$ which are at the same level can join up by atoms filling in the lower level C to form a bridge. This stage is shown in fig. (38b). The parts $D$ and $E$ of the step grow very rapidly since the curvature is negative; that is the length of the step decreases as the step advances. Thus a closed loop has been generated and in the final stase, the step has returned to its original position and is ready to start again to go through the above cycle qgin. Therefore, as successive loops are developed the surface of the crystal becomes a pyramid, which will be composed of sheets or molecular layers. This development of the growth step is illustrated in three dimensions in fig. (39).

Fig. (35) shows this behaviour for circular spirals. In the left half of the figure, one right handed and the other
left handed screw dislocation emerge on the crystal surface. The spiral attached to the left handed screw dislocation is developed for about three turns when it meets the ledges originating from the right handed screw dislocation. Thereafter, in accordance with theory, successive closed loops are generated. These loops are circular for the most part with only a slight distortion over a small portion. The step height of these circular spirals has been measured to be 15A, the crystal being of type 6 H .

Fig. (40) shows a unique case of two screw dislocations of opposite sign close to each other and equally developed. Here the spirals have straight edges. The resultant growth pattern consists of closed sheets except at the centre where the layer is incomplete and shows its formation from two screw dislocations of opposite sign. The closed loops are triangular at the centre, but on going away from the centre, become hexagonal, with three alternate edges longer. The stepheight i.e., the thickness of each layer has been measured to be nearly 120A, see fig. (107) and this indicates that these features occur on a polytype with a large unit cell (see Sec. 10.2).

Fig. (41) which is a bright-field phoograph of an unsilvered crystal, shows two dislocations of opposite sign each giving rise to a hexagonal spiral. When the successive
arms of the two spirals meet each other, they generate closed loops. At the points of intersection, an edge can be observed, indicating that the levels of the two steps joining together are not the same.

Another rare case is shown in Fig. (42) which consists of closed hexagonal sheets with no trace of dislocations at the centre. The closed hexagonal figures might have originated from two dislocations of opposite sign, alternatively there may be some other mechanism.

### 7.4. DISCUSSION OF THE OBSERVATIONS ON PAIRS OF

## SCREW DISLOCATIONS

When two dislocations of opposite sign emerge on the crystal face, they interact with each other. The forces exerted between them have been calculated by Taylor (1934) for two edge dislocations. The radial force $F_{R}$ and the tangential force $F_{a}$ are given by the relations:

$$
\begin{aligned}
& F_{R}=-\frac{G \lambda^{2}}{2 \pi(1-\nu)} \frac{1}{R} \cdots \cdots(37) \\
& F_{a}=-\frac{G \lambda^{2}}{2 \pi(1-\nu)} \frac{\sin 2 \alpha}{R} \cdots \cdots(38)
\end{aligned}
$$

Where $G$ is the shear modulus of the material; $\nu$ is the Poisson's ratio, and $\lambda$ is the dislocation strength; $R$ is the distance between the two dislocations, and $\alpha$ is the
angle which the line joining the two dislocations makes with the $x$-axis. Hence dislocations of opposite sign attract each other with a force that varies as the reciprocal of the distance between them. For dislocations of the same sign, the above expressions are reversed in sign and therefore the dislocations repel each other.

There is however a constraining force anchoring these dislocations to their equilibrium positions between the lattice rows. Peierls (1940) first calculated this force, which was later on extended by Nabarro (1947). They find that this force depends upon the elastic constants of the medium. According to Nabarrols calculation, the stress required to move the dislocation by overcoming the constraining force is:

$$
\sigma_{t} \cdot \frac{4 \pi}{1-\nu} e^{-2 \pi /(1-\nu)}
$$

$$
-------(39)
$$

where $\sigma_{t}$ is the theoretical shear stress for a perfect lattice $(\simeq G / 10)$, and $\nu$ and $G$ are as previously defined.

This, does not take into account the strength of the dislocation, on which, this force should depend in some way.

At a certain distance of separation between the two dislocations, these forces viz: the attractive and the anchoring forces will balance each other. During the process
of growth of silicon-carbide crystals, when the temperature is high, the two dislocations of opposite sign will draw towards one another and will finally coalesce, joining to form a common centre (which is a hollow core), unless the distance of separation is more than the above equilibrium value.

Experimentally, pairs of dislocations of opposite sign are seldom observed. Amongst all such pairs observed so far on silicon-carbide, a pair of dislocation of opposite sign close to each other such that the two spirals are equally developed (i.e. the first, second, etc., arms of the spiral from one dislocation meet the corresponding arms from the other) has not yet been observed for the dislocations of the elementary Burgers vector of small step height (e.g. 15 A for type 6 H). However, for a comparatively larger Burgers vector one such pair of close dislocations equally developed has been observed. This rare case is the one show in fig. (40). Since its step height is nearly 120A, this is possibly due to the constraining force depending upon the strength of the dislocation i.e. the Burgers vector.

The closed sheets of fig. (42) have a very faint visibility and consequently the step height is small. In this case, the two dislocations of opposite sign can be drawn sufficiently close to each other. When they are separated by a distance such that the critical nucleus cannot pass
between the two, the growth will cease and no new closed loops will be generated.
7.5. GROWTH PATTERN FOR THREE AND LARGER NUNBER OF DISLOCATIONS
(a) Growth Pattern for Three Screw Dislocations

The growth pattern for three or a larger number of screw dislocations can now be explained. The growth pattern for three screw dislocations of the same hand observed on a crystal of type 6 H is illustrated in fig. (43). Once more the spirals are circular at the centre and become hexagonal after a few turns. In the central part the three dislocations are at a distance such that the ledges from them intersect and fuse with one another so that the growth pyramids interleave. When the spirals finally become hexagonal, they cooperate with one another, so that by following any one of the edges, the resultant curve descends by three units in each turn. However, it shoud again be emphasized that the step height between successive edges in any orientation will be only one unit.

At the centre the ledges are more closely spaced and once they have settled down, the ledges are more widely spaced. This may be attributed to the high supersaturation of the final stage of growth. This will also explain the non-co-eperation of the three dislocations separated by these distances, since with the increase of the supersaturation the
radius of the critical nucleus will decrease and for the same distance of separation between the dislocations, they may be separated by distances larger than $P_{C}$. In the earlier phase, when the spirals have wider spacing, the two spirals on the right co-operate and dominate the one on the left. This can be seen from the shape of the first widely separated spiral turns.

## (b) Five Separated Screw Dislocations

Fig. (4) illustrates the interaction of five screw dislocations. Starting with the double screw dislocation at the extreme right and calling it $A$, the lower of the two may be called $A_{1}$ and the upper one $A_{2}$. The screw dislocation points at the top, left, and bottom of the figure are called respectively B, C, and D. At a point which is slightly to the right of the centre of the figure, a dowding of growth fronts occurs, This point which is at the end of a line of discontinuity running to the centre of the figure from left to right, may be called 0 . Between 0 and $B$ there are five growth fronts as arcs of circles emitted by the dislocation point $A_{1}^{\prime}$. The 6th. growth front meets the growth front advancing from $B$, and at the middle part for nearly over 1 cm . they fuse with one another, and over the common portion annihilation occurs. The compound growth front assumes a characteristic shape of $\Omega$. This behaviour continues for the 7th. and the following growth fronts until we come to the

13th. growth front. The 13th. growth front meets the growth fronts advancing from $C$ where again over a small portion of it, annihilation occurs. Now the compound growth front assumes another characteristic shape $\Omega \Omega$. The portion of the 13th. growth front on the lower side of the annihilated part is not wholly an arc of a circle with $A_{I}$ as centre. It has a point of inflexion and the lower portion bends to the left when it meets the boundary or the line of discontinuity, coming diametrically from the left of the figure. This kink to the left can be seen in the l2th., 1lth., 10th., 9th., and possibly 8th., and 7th., growth fronts. Beyond the 13th., growth front towards the point C, growth is dominated by $C$. In the lower portion of the 13th., growth front a small shaded area is visible near the line of discontinuity, the left edge of which is an arc of circle with $C$ as centre. This shading can faintly be seen in the lowest part of the l2th., end possibly the llth., growth fronts.

At $O$ due to the interaction of different growth fronts a crowding occurs. Here the compound growth fronts are not arcs of circles with the different dislocation points as centres, but instead there is a gradual change in curvature.

Fig. (45) shows the growth pattern due to the emergence of six screw dislocations, all of the right-handed type. Here again the step lines are nearly circular at the centre, finally becoming straight. Since the group of
dislocations is near the edge of the crystal, the resultant growth pattern is not fully developed on all sides.
7.6. RESUITANT GROWTH PATTERNS FOR A VERY IARGE NUMBER OF DISLOCATIONS

Interaction of Growth fronts and Curves of Intersection

## (i) General Case

When a large number of dislocations emerge on the surface of the crystal, the resultant growth patterns are quite complicated. Figs. (46), (47) and (48) illustrate some examples. In fig. (46) the step lines are all circular, whereas they are polygonal with rounded corners in figs. (47) and (48). These complicated growth patterns arise by the interaction of the growth fronts spreading from the various sources. Some of the properties of the growth fronts have been outlined in section (7.2). Some further general principles that govern their interaction, and the shape of the locus of points of intersection will now be given.

The successive arms of the spirals originating from any two dislocations can join with each other only if the two dislocations are of the same strength i.e. the two step heights are equal. Conversely if successive steps from two dislocations join and fuse together, it can be consluded that the step heights of the two spirals are equal. Since this joining
together of steps is observed in figs. (47) and (48) for the successive steps from all the interacting dislocations, the step height must be a fixed unit and its measurement on any one of them will give the value of all the rest. Therefore it ma $y$ be concluded that $t$ in any one region of the crystal, the dislocations have the same strength.

If then the $n^{\text {th }}$ step from one source $O_{1}$ meets the $m^{\text {th }}$ step from the other sources $\mathrm{O}_{2}$, they will join together if they are at the same level. Thereafter pairs of steps that can join together are $(n+1)^{\text {th }}$ with $(m+1)^{\text {th }} ;(n+2)^{\text {th }}$ with $(m+2)^{\text {th }}$ etc., such that $t$ the order difference between these steps fusing vi. th one another is always constant and equal to $(n-m)$. Microscopically speaking, on either side of the locus of points of intersection, the portions of the two pyramids should slope in the same direction, ie. on travelling along this locus of points of intersection we will be moving from a higher to a lower level, or vice versa, for both the pyramids. Examples of this can be seen in figs. (47) and (48).

Further, if the spacing between the $n$th and the $(n+1)^{\text {th }}$ arms of one spiral is $d_{I}$ and between the $m^{\text {th }}$ and the $(m+1)^{\text {th }}$ arms of the other is $d_{2}$, the two pairs of steps will meet the locus of points of intersection at angles $\theta_{1}$ and $\theta_{2}$ respectively, such that

$$
\begin{equation*}
\sin \theta_{1} / \sin \theta_{2}=d_{1} / d_{2} \tag{40}
\end{equation*}
$$

The value of $\left(\theta_{1}+\theta_{2}\right)$ at a particular point of intersection is fixed by the initial conditions of the distance of this point from the two sources, the distance between the two sources and the shapes of the two spirals.

In the more general case $d_{1}$ and $d_{2}$ are the lengths of perpendiculars dropped from the point where the $(n+1)^{\text {th }}$ and $(m+1)^{\text {th }}$ arms meet each other, upon the tangents drawn to the $n^{\text {th }}$ and $m^{\text {th }}$ arms of the two spirals at the point where they meet. The tangents to the $n^{\text {th }}$ and $(n+1)^{\text {th }}$ arms of one spiral may not be parallel to each other, so that not only the spacing between the successive arms changes, but also their directions may change, in which case the locus of points of intersection will have to turn suitably in order to satisfy the above sine condfion. This is illustrated in fig. (49) where with the change of direction by the steps through an angle about $60^{\circ}$, the locus of points of intersections also turns through a simila $r$ angle. Other examples of the interaction of growth fronts and the loci of their points of intersection in accordance with the above conditions are seen in figs. $(47)$ and (48), where a large number of polygonal spirals with varying spacings are interacting with one another. Another example of the interaction is seen in fig. (50) where as a result of the meeting of the growth fronts from three dislocations at the centre of the figure closed triangular loops are formed. (The figure includes only two
out of these three interacting dislocation centres. The third one will be towards the bottom of the figure).

If the two series of steps originating from two dislocations, on reaching the same region of the crystal, are unable to satisfy any of the above conditions, e.g. sine condition, they will not join with one another. These steps will then terminate in such a region. The points where the steps terminate will be ends of screw dislocations, Such a behaviour is seen in fig. (48) along a dotted line (running from nearly left to right in the middle of the figure) with a small gap in the centre, over which region four steps of the two spirals are seen to join together. We can reach any one of these four steps (say the second from the left) from a point A in a number of ways. In going from $A$ to the chosen step we have to go down 30 steps, this number being independent of the path taken. A direct path can be traversed or one involving the crossing of different hexagonal spirals by going round the right hand end of the line of discontinuity. This is to be expected since the different spirals are of the same strength.

> Fig. (51) illustrates another example where the spiral
edges, though having the same step height, are unable to fuse with one another. These two series of step lines with their spacing nearly in the ratio $1: 2$ happen to meet each other at right angles. They cannot satisfy the sine condition and
therefore the steps have to terminate. Thus they create a barrier of dislocations between them, shown as a dotted line of discontinuity running nearly vertically across the rijddle of figure. Figs. (53) and (54) are further examples of the termination of the step lines. In fig. (54) at every point of termination of the step lines a dot can be seen. This may be due to the depos ition of impurity at these points.
(ii) Special Case : Circular Spirals

The exact shape of the curves of intersection can be calculated in the simple case of rounded spirals. By introducing the approximation used for the interferometric measurements of step heights, according to wich these spirals may be regarded as composed of circles of constant spacing $\delta_{r}=4 \pi \rho_{e}$, the condition $(n-m)=$ constant, directly gives the locus of the point of intersection $P$ of the two rounded spirals originating from the two source centres $\mathrm{O}_{1}$ and $\mathrm{O}_{2}$. Thus $(n-m)$. $\delta r$ will be a constant from which we have $O_{1} P-$ $\mathrm{O}_{2} \mathrm{P}=$ constant. This gives the locus of the point of intersection, a hyperbola which for $(n-m)=0$ reduces to a straight line perpendicular to $\mathrm{O}_{1} \mathrm{O}_{2}$ and passes through its middle point (Burton, Cabwera and Frank, 1951).

A locus of points of intersection, which is hyperbolic, is illustrated in fig. (33) for two circular spirals unequally developed. The condition $(n-m)=0$ corresponds to the symmetrical case of two spirals equally developed and is
illustrated in the upper half of fig. (52) where the locus of points of intersection for two spirals equally developed is seen to be nearly a straight line, perpendicular to the line joining the two dislocation points and passing through their middle point. Here the two series of steps with equal spacing (i.e. $d_{1}=d_{2}$ ) meet the locus of points of intersection at equal angles $\left(\theta_{1}=\theta_{2} \neq 0\right)$. In fig. (33) as the spacings of the two spirals become equal (i.e. $d_{1}=d_{2}$ ), in accordance with the sine condition $\theta_{1}$ will become equal to $\theta_{2}$, and in this case the steps tend to be parallel to each other at the points of intersection (i.e. $\theta_{1}=\theta_{2}=0$ ).

As shown by Burton, Cabreaa and Frank (1951) a small influence is transmitted along each step from the points where the two spirals meet, into the respective centres. This will tend to increase the rate of rotation of the spiral whose centre is nearer the points of contact the upper one in fig. (33) ) trying to synchronize the two in phase. This will smooth out the corners formed by the meeting of the two series of steps. This is observed in all the interacting spirals.

### 7.7. STATISTICAL PROPERTIES : DENSITY OF DISLOCATIONS

For a very la rge number of dislocations emerging on the surface of the crystal, in addition to the study of the individual behaviour of the dislocations, certain statistical properties of the whole population can be studied, the chief
amongst them being the density of dislocations, their type and strength.

The density of dislocations varies widely on different specimens of silicon-carbide (Si-C) crystals. In figs. (16b) (22), (25) etc., there is only one dislocation, the growth fronts from which fill the whole surface. In figs. (21), (24), (33), (34), (36) there are several. The largest density of dislocations observed, for circular spirals is shown in fig. (46), and for polygonal spirals in figs. (47) and (48). In fig. (4,6) the density of dislocations is $\sim 10^{4}$ screw dislocations per sq.cm. of the crystal surface whereas in figs. (47) and ( 48 ) it is $\sim 10^{5} / \mathrm{cm}^{2}$.

A note worthy point is that in fig. (46) there are nearly 20 screw dislocations all of which are of the rightha nded type. Similarly all the polygonal spirals shown in figs. (47) and (48) a re of the left-handed type. Thus, it is characteristic that in any one region of the crystal, there is a large predominance either of right-handed or left-handed screw dislocations.

Further, as discussed in section (7.6) the series of successive steps from any two screw dislocations in figs (47) and $(48)$ are observed to fuse with one another. This can only be explained if the step-heights of the two series of steps, originating from the two dislocations are the same i.e. the two dislocations are of the same strength. Since
this is true for all the dislocations in figs. (47) and (48), it may be concluded that in any one region of the crystal the dislocations have the same strength.

Thus it is characteristic that in any one region of the crystal, the dislocations are not only predominantly of the same sign but also have the same strength.

### 7.8. FAULT SURFACES

The interaction of two dislocations of unequal strength may be considered now. When two steps advancing on the same level towards one another, from two sources, weet each other, the result is dependent upon the nature of the step wail. Three cases will arise.
(i) If the two step walls are identical i。e. are composed of the same number of molecular layers their relative arrangements being the same, they will fuse together forming an unbroken erystal surface. Thus in fig. (3I) where the simple case of the interaction of two identical dislocations is represented, between the points $p_{1}$ and $p_{2}$ where the two steps have fused with one another, the surface of the crystal is flat and unbroken. In the case of silicon-carbide, which is a polytypic crystal, there are several possibilities of forming identical steps, attached to the two dislocations e.g. both of them may be of a type with Zhdanov symbol (33) or (32) or (33 32) etc., the step heights being the simple
units for these types. Figs. (36), (44), (46), (47) etc., come under this category.
(ii) The second case will arise when the two step walls consist of the same repeat unit but have different step heights e.g. both may be of a type with Zhdanov symbol (33) but they may be different multiples of this structure, say, $n$ (33) and m (33), (see Chapter 8). In this case, since the structure of step walls is identical, they will fuse with one another but since their step heights are unequal, they will leave a step of height equal to the excess of the repeat unit of one over the other - equal to $(n-m)(33)$ in the above example.

Fig. (55) illustrates this case. Here, over the part where the steps from the two hexagonal spirals meet and fuse with one another, a faint step can be seen running between the two points of contact. Since the two dislocations are of opposite hand and the faint step line follows the step lines of the spiral on the left hand side, it may be consluded that the dislocation on the left hand side is the stronger.

Fig. (41) was another example where two dislocations of opposite sign each give rise to a hexagonal spiral. At the points of intersection an edge can be observed, indicating that the levels of the two steps joining together are not the same. Further examples are shown in figs. (56), (57) and (58). Figs. (57) and (58) are the enlargements of upper and lower
portions respectively of fig. (56). In fig. (58) the faint step line which gives the excess of one step height over the other can be seen clearly.
(iii) In the third case, the two dislocations may be of different strength and also may have different structure. The two step walls will now consist of different numbers of layers and will also be differently arranged. Thus for example, one dislocation may be of a type with Zhdanov symbol (33) and the other with (32). In this case the two steps cannot fuse with one another in a perfect way crystallographically. They will leave a line of discontinuity which will maris out a fault surface.

Examples of fault surfaces are shown in the following figures (59 to 63). Consider fig. (63). As the growth steps on the right hand side of the figure originating from a screw dislocation not included in the figure, advance into the loop formed by the line of misfit, it shows that the crystal material inside the loop is crystallographically perfect and may be termed a "good crystal". (For definition see Frank 1951 I \% \% Therefore, misfit in the crystal lattice is confined to the boundary line. The step lines are observed to meet the boundary line at sharp angles creating re-entrant corners, which shows that the step marking out the fault surface does not advance appreciably, and may act as a barrier to the progress of growth layers. It is possible that the lines of
discontinuity seen in different figs.e.g. (36), (44), (46) etc., may be of this nature.

Furthermore, the different dislocations in any one region of the crystal may have originated from one dislocation with a large Burgers vector. As the step associated with the large Burgers vector will not terminate abruptly, but macroscopically speaking taper away, it will actually break into discrete dislocations and most likely into dislocations of unit Burgers vector. However, amongst the group of dislocations, those which are different in structure from the majority group, will give rise to the misiit surfaces and will be locked at the barriers, leaving only those dislocations, the step lines from which fuse with each other perfectly. The dislocation with a large Burgers vector will naturally break into component dislocations which are of the same sign. Since like dislocations repel each other, they will tend to spread apart as growth proceeds.

This may offer an explanation to the significant observation that in any one region of the crystal, the dislocations are of the same sign and have also the same strength.
7.9. GROUPS OF DISLOCATIONS : SOME GEOIETRICAL PATMERNS

Quite often groups of dislocations arranged in different ways emerge to the surface of the crystal and the growth patterns take complex geometrical shapes. A group of
some 50 dislocations of the same sign arranged along a line of length $I$ is seen in fig. (64) to generate a spiral system of $s$ branches. The resultant activity of the group will be

times that of a single dislocation (Burton, Cabrera and Frank 1951), where $\rho_{c}$ is the radius of critical nucleus defined by equation ( $16^{\circ}$ ). Fig. (65) illustrates another such group where steps are seen to group together giving a repeat pattern.

Some further examples of these geometrical patterns are given in the following figures $(66$ to 69$)$. In all these figures, a bunching together of steps has taken place. Fig. (67) shows the interaction of two groups of dislocations. At the points where the series of steps from these two sources meet each other, the step lines are observed to fuse with one another, This will be possible only when the step walls originating from the two dislocations have the same structure. Further, since the steps originating from the two dislocations are not elementary, the two series of steps on either side of the locus of points of intersection, can fuse with one another if they can bunch or dissociate into smaller steps so as to bring the crystal level on both sides the same. That this is so, is seen in fig. (67) where on
either side of the locus of intersection, there is a continuity in the arrangement of step lines.
7.10. SONE RESUITS ABOUT THE CONDITIONS OF GROWTH

The different information which can be derived, from the microscopic observations, about the conditions at which the growth of silicon-carbide crystals took place are, the radius of critical nucleus and the supersaturation. From figs. (36) and (4), the spacing between the successive arms of the circular spiral, when it is nea戶̄ly constant is, approximately, $2.5 \mathrm{~m} . \mathrm{m}$. at a linear magnification of 90 . From equation (36)

$$
\delta r=4 \pi \rho_{c} \quad \text {, we have }
$$

$$
\rho_{c}=\frac{2.5}{90 \times 4 \pi} \mathrm{~mm} \approx 2 \mu \quad \ldots . .-(42)
$$

This gives the size of the critical nucleus to be about $4 \boldsymbol{\mu}$. The supersaturation can be calculated from equation (16) viz.

$$
P_{c}=a \phi / 2 k T \ln \alpha
$$

provided $\phi / k T$ can be estimated. For this estimation Trouton's rule may be used according to which

$$
\frac{\phi}{k T}=3.5 \quad T \mathrm{~B}
$$

and at an absolute temperature of 0.6 of the boiling point of the material $\frac{\phi}{K T} \sim 6$. Substituting, the supersaturation $\alpha$ is given by

This shows that the crystals grew at firly low value of supersaturation.

## CHAPTER VIII

## SPIRALS ORIGINAMING FROM DISIOCAIIONS OF HULTIPIE

## STRENGTH AND IUUTIPIE DISLOCATI ONS

### 8.1. IARGE STEP HEIGHTS AND DISLOCATIONS OF MULTIPIE STRENGTH

The step formed by the emergence of a screw dislocation on to the crystal surface will have a step beight corresponding to the differences in the amounts of slip between neighbouring regions of the crystal. Because of the existence of discrete atomic structure in the glide plane, this will be limited to the value of the X-ray unit cell of the crystal or in some lattices a small multiple or fraction of this. The spirals discussed in Chapter (VII) are of the simple type in which the step heights are equal to the heights of the X-ray unit cell e.g. in type $6 H=15 A$ (See Chapter $X$ ). Because of the small step heights the visibility of these spirals was low.

The spirals described below, have a much higher visibility and interferometric measurement shows that they have relatively large step heights; indeed, they can often be seen simply with a microscope using bright-field illumination without silvering the crystal. However, the following figures have been taken using the silvering technique and observing them with phase contrast illumination.
As silicon-carbide (Si-C) is a polytypic crystal, a
large step height may be due to its being equal to (I) the height of a large X-ray unit cell (2) a multiple of a smaller X-ray unit cell. The latter type of spiral results from a dislocation of multiple strength, the Burgers vector being a multiple of the X-ray unit cell.

### 8.2. DISSOCIATION OF STEPS

Fig. (70), which is a bright-field photograph of an unsilvered crystal face, illustrates a spiral originating from a dislocation of multiple strength, observed on a crystal of type 6 H , as determined goniometrically (see Sec. (10.2) ). The central part of the spiral of fig. (70) is shown in fig. (104), using phase contrast illumination. From the shift of the Fizeau fringes (fig. (105) ) over these spiral steps, the step height between the successive arms of the spiral has been determined to be nearly 620 A .

The rate of advance of a multiple step will be controlled by the deposition rate at the bottom of the step (Frank 1951 a) and as long as the bottom of the step is not privilesged with respect to the diffusion of the molecules from the gas, the multiple step will not dissociate into its component steps. In fig. (71), showing the right half of the spiral in fig. (70) using phase contrast illumination, the edges do not remain straight after three or four turns from the centre and become irregular. This behaviour continues for a few more turns after which the steps dissociate into five
visible components (see fig. 72). The edges of these multiple steps will not be close packed. The Fizeau fringes (fig. (105)) passing over these steps are seen to be continuous over the edges of the steps while climbing them. This indicates that the edges are not steep. Furthermore the crystal face between the successive edges is not close packed. This is illustrated by fig. (72), which is an enlargement of the right hand portion of fig. (7I), where some faint step lines can be seen between successive edges. Figs. (73) and (73a) show the behaviour of the steps on the left part of fig. (70).

The dissociation of a step into iṭs components takes place preferentially in certain orientations. In figs. (71) and (72), the dissociation has taken place preferentially in one orientation, and at $60^{\circ}$ to this direction, this dissociation is much less marked. Fig. (74) is a better example showing the dissociation on the three alternate sides of the hexagonal spiral. This is easily comprehensible since in Si-C, a growth layer which is fastest in any one orientation becomes slowest in orientatiens at $60^{\circ}$ to it; the faster moving steps will overtake it and pile up behind.

Fig. (75) shows the spiral growth pattern observed on a crystal of type 33R. Here two spiral step lines start from a cormon hollow. They stay as two separate steps for about half a turn, after which the step lines come closer together finally touching each other along an edge, after which they
separate out and remain as two for the rest of the turns. This behaviour is in contrast to that observed in fig. (74).

A spiral showing trigonal symmetry with three corners rounded, is illustrated in fig. (76). The step-lines reach the edge of the crystal after it has developed for nearly two turns. However, the spiral continues to unfold itself, and as seen at the lower right hand corner of the figure, the steps separate out into two components giving each step line the appearance of a broad line.

### 8.3. MUITIPIE DISLOCATIONS

Dissociation is seen to take place quite near the origin in the example shown in fig. (78). Here amongst the dissociated steps, in three orientations, the outermost edges (which correspond to the bottom layers of the group) are straight and parallel to each other in the successive arms of the spiral, whereas at the inner edges, the usual irregularity is observed. Fig. (77) shows separately the third and the fourth arms of the spiral of fig. (78).

> Figs. (79) and (80) illustrate further examples of multiple dislocations. In fig. (79), in contrast to fig. (78), the growth is faster at the six comers, the rate increasing towards the outer (or bottom) layer in the group. At some of these corners crosslacing of the step lines (See Chapter IX) is observed and may be responsible for the faster growth (c.f. figs. (92) and (93)).

## INTERIACED SPIRALS

### 9.1. SIMPIE INIERLACED SPIRALS

## Observation

This is a new type of spiral which was not predicted by theory. The following figures (81 to 99) illustrate 'spirals' belonging to this type. As seen in fig. (81) and other subsequent figures the appearance of these spirals is similar to that of a spider's web. This appearance arises because in each of these hexagonal spirals at the six corners the edges fork out and meet the neighbouring two edges, and since this happens at the six corners for all the steps, a criss-cross appearance results. These interlaced spirals may be divided into two classes, firstly simple interlaced spirals and secondly banded interlaced spirals in which a certain number of steps group together.

Fig. (81) illustrates simple interlaced hexagonal spirals, showing interlinking of four such interlaced spirals. Fig. (81) is the usual phase-contrast micro-photograph. The much higher visibility of fig. (82) showing the same part of the crystal has already been commented upon in Sec. (5.2 e).

Fig (83) shows the interlinking of two interlaced spirals at a higher magnification (xl200). In the middle of fig. (84) a single interlaced spiral is shown, whose central
few turns are very closely spaced, after which, the spacing suddenly increases. Here the step lines follow a pattern which resembles fig. (88). From the first widely spaced step lines, on moving towards the left, in the middle of the $8^{\text {th }}$., step line the emergence of another small interlaced spiral can be observed. This interlaced spiral remains under the domination of the central one, its behaviour being very much similar to the behaviour of domination as outlined for simple spirals in section (7.2); it merely passes on, the growth fronts received from the central dominant screw dislocation and slightly alters the shape of growth fronts as they pass near it. This is a unique example showing the phenomenon of domination in the case of interlaced spirals. Some further examples of these interlaced spirals are shown in figs. (85) and (86).

## Explanetion

An explanation of this has been given by Frank (1951a) and depends upon the dependence of growth rate on crystallographic directions and the change of the growth rate of the monolayers in different orientations of the crystal. Considering say the silicon-carbide of type 6 H , its Zhdanov symbol is (33). Using Frank's notation it may be written as

## $(\Delta \Delta \Delta \nabla \nabla \nabla)$

These six monolayers together, form the $X$-ray unit cell, and will form a step of height 15 A . In this sequence of six
monolayers, the force field for each monolayer is slightly different, and therefore one of these monolayers will have the slowest rate of growth. The other, faster moving, monolayers will overtake it and pile up behind it, forming a step of height corresponding to the whole repetition period. Thus the slowest growing monolayer will be at the bottom of the stack of monolayers and would determine the rate of growth of the stack as a whole. As long as the conditions of growth are such that the monolayers in the stack are not separated from one another, this pile will advance as a single unit and will constitute a single step line, so that in any one orientation of the crystal, step lines 15 A high corresponding to each stack of monolayers will be observed. But it is not certain that the slowest growing monolayer in one orientation say (oII) will also remain the slowest growing in orientations $60^{\circ}$ to it i.e. (10T) orientation. In fact, in type 6 H , the slowest growing monolayer in one orientation should become the fastest in orientations at $60^{\circ}$ to it. This is easily pictured from Frank's notation, which has memonic representation also. According to this, a monolayer which is represented by $\Delta$ in a certain orientation will be represented by $\nabla$ at orientations $60^{\circ}$ to it, since a $\Delta$ changes into a $\nabla$ by rotation through $60^{\circ}$. Hence on alternate sides of the hexagon, the growth layers form alternate groupings of

$$
(\Delta \Delta \Delta \nabla \nabla \nabla) \text { and }(\nabla \nabla \nabla \Delta \Delta \Delta)
$$

Thus, whichever layer is the slowest growing one in a
particular orientation, say the first $\nabla$ after a series of $\Delta s$, then the third layer after it is necessarily the slowest growing in orientations at $60^{\circ}$ to it. This alternation of velocities will lead to the interlacing of the growth steps. This is represented diagrammatically in fig. (87). Here in the stack of six monolayers the fastest growing layer is marked $F$ and the slowest $S$. Between these two monolayers there are four other monolayers with intermediate rates of growth and for the sake of clarity these have not been drawn. Further the separation between the $F$ and $S$ layers is exaggerated; actually they are so closely piled up on each other, that the whole forms a single step 15 A high. The $F$ layer is shown to become $S$ layer and vice versa when the orientation changes through $60^{\circ}$. Thus the growth layers will be 6 layers high i.e. 15A high on the six sides of the hexagon, and only three layers high on the zig-zags, at the six corners i.e. the step height will be 7.5A. Amelinckx (1951a)has measured the step height of an interlaced spiral, similar to tha $t$ shown in fig. (88), to be $7 \pm 2 \mathrm{~A}$. This is in accordance with the above explanation.

Fig. (88) showing alternate trigonal spirals, assists in the above interpretation. Here, in any orientation, the three layers are separated from the other three and the figure has trigonal symmetry. This is to be expected since the symmetry of any one of the monolayers, in the stack of monolayers,
advancing over another is trigonal. Fig. (89) is another illustration of interlacing of two trigonal spirals.

### 9.2. SOIE FURTHER EXAMPIES

Figs. (90) and (91) illustrate an example of interlaced spiral in which the structure of the step lines on the a.lternate sides of the hexagon is markedly different. In three orientations, alternate step lines are rugged and irregular whereas in the other three orientations all the step lines are smooth. In the part $A B C$ of fig. (91), the step lines are smooth, and in part $A C D$, alternate step lines are irregular and have a rugged structure. The continuity of alternate smooth step lines in $A C D$ can be traced to $A B C$. The transition along the zig-zag portion AC is clearly shown in the figure. This rugged appearance of step lines may be due to slight surface oxidation, causing the layers to separate out in certain orientations.

Figs. (92), (93) and (94) showing the same feature in three different magnifications illustrate another interesting variation of interlaced spirals. The point of special interest here is that the six corners appear to grow faster than the straight portions. This results in the step lines, between any two corners, having a cusp and a concave form. According to theory, a step with a re-entrant corner or with a negative radius of curvature should rapidly grow out. This cusp in the
step line and its concave form could only have been maintained by the faster growth at the six corners, this pull along these corners giving the hexagonal figures the above shape. In fig. (94), which shows the centre of the spiral, it is seen tha $t$ the step lines are convex near the centre, their curvature decreasing with the increase of the distance, in accordance with theory.

A point which can be noted in all these figures of interlaced spirals is that at the six corners, the extent of the zig-zag or criss-cross pattern varies in different cases. In some of them e.g. figs. (82), (85) and (86) this is. limited over a small area and the transition appears quite sharp. Whereas in other figures such as (84) and (91) this transition from the slowest to the fastest monolayers by changing the orientation through $60^{\circ}$ is gradual and smooth. Further over this transition area the zig-zag portion of the interlaced spiral may be composed of small straight lines as illustrated in figs. (83), (85) and (86) or it may be gradually curved as seen in fig. (84). In the diagram fig. (87), the transition portion has been drawn, for the sake of simplicity, as straight lines.

This alternation of the velocity of growth with the change of orientation by $60^{\circ}$ will necessarily occur in the hexagonal type 6 H , but it is possible that it may occur in
the rhombohedral types also, in which case the rhombohedral types will also display these interfed spirals. According to this explanation since the change of growth velocity will necessarily occur for spirals developed on crystals belonging to type 6 H , they should always interlace. But crystals of type 6 H have been observed to exhibit circular, hexagonal, as well as interlaced spirals. Therefore, this explanation, though It gives a qualitative explantion, is incomplete and there must be some other factors also controlling the formation of these spirals.
9.3. GROUPED INTERLACED SPIRALS AND ITS EXPLANATION

In some of the interlaced spirals a grouping of a certain number of steps takes place. Several such cases have bee $n$ studied and the number of steps grouping together has been found to vary depending upon the number of layers in the x-ray unit cell of the crystal. Fig. (95) shows part of an interlaced spiral in which in any one orientation seven steps are observed to group together having a characteristic sequence of spacing between them. These steps can be followed in fig. (98), which shows spiral as a whole at a lower magnification, to the other side of the interlaced portion, and the same sequence of spacing repeating itself is observed. This characteristic spacing between the successive seven steps is seen to repeat itself for the successive groups. Mnder low magnification, these grouped steps give an appearance resembling optical band-spectra. In fig. (96),
showing a different portion of the same spiral, it is seen that the high visibility of the step lines is due to the deposition of some impurity. In fig. (97), the advancing groups of seven steps meet the interlaced steps originating from three new screw dislocations. The figure illustrates their interaction.

On another crystal a similar grouping of five steps has been observed. This is illustrated in fig. (99). Unlike the previous example the grouping of five steps together cannot be followsd to the other side of the interlaced portion since the interlaced portion is near the crystal edge. The spacing between the successive five steps is not constant and therefore it does not have the characteristic appearance of figs. (95) and (97).

In addition to these fixed number of steps grouping together, on one face of a crystal, the number of steps grouped together ha s been observed to change in certain regions. Thus in fig. (l00) which exemplifies this type of behaviour, it is observed that the number of steps that have grouped together varies greatly on different parts of the crystal.

## Explanation

An explanation of these features can be given as follows. (Verma l951 $\mathbb{a}$ ). The different polytypes of silicon-
carbide have the Ramsdell's zig-zag sequence or Zhdanov symbol of (33) 32 . Using Frank's notation, the structure can be written as:

$$
[(\Delta \Delta \Delta \nabla \nabla \nabla) n \Delta \Delta \Delta \nabla \nabla]
$$

As in the previous case of simple interlaced spirals, the growth conditions will be different for each of the Si-C layers provided atomic interactions are significant as far away as the number of layers involved. The most striking difference will occur at each change in the $\Delta \nabla$ sequence i.e. when' the first $\triangle$ layer occurs after a series of $\nabla$ layers or vice versa. Now it is not known whether this will make the rate of advance faster or slower. If it makes the layer grow faster, it will not produce an observable change and hence is unimportant. If, however, it makes it grow slower then a certain monolayer in this stack of monolayers will be the slowest one and the faster following layers will pile up on it, pto and excluding the next one which goes at the same rate. Thus if we assume that the first $\Delta$ after a series of $\nabla_{s}$ (or vice versa) has the slowest velocity in any one orientation, then it will repeat itself after six such layers making the growth steps 15A high, until we reach the last layer which will be 12.5A high, since it is composed of only five monolayers. After this, the whole sequence will go on repeating itself. The case for seven steps grouping together is represented as follows:-

Thus depending upon the number $n$ in the Zhdanov symbol $\left[(33)_{n} 32\right]$ we will have a certain number of steps grouping together.

In figs. (95) and others the seven steps grouped together form the unit cell and hence the step height at successive edges is only a fraction of the unit cell. Similarly the step heights of all other grouped steps is also a fraction of the unit cell. These steps further break up into two parts i.e. each is only 3 monolayers high, over the interlaced or zig-zag part.

The observation of the changing number of steps grouped together suggests a change in type from one part of the crystal to another. The different parts of the crystals showing grouping of say 9, 11, etc., steps means that those parts of crystal are the polytypes with Zhdanov symbol $\left[(33)_{8} 32\right],\left[(33)_{10} 32\right], \ldots-$ etc. This may account for the disagreement between crystal symmetry and $x$-ray diffraction data sometimes observed (Ramsdell Rohn 1951)

The observation of this grouping of steps is another visual confirmation provided by crystal growth patterns, of the repeat sequence predicted by x-ray phenomena.

## CHAPTER X.

## RESUITS OF INTERFEROMETRIC STUDIES AND POIYYYPISM

## IN SILICON-CARBIDE

By the application of multiple-beam interferometric techniques as outlined in Chapter VI, the step heights for the growth spirals observed on different Si-C crystals were measured. As shown below, the step height between successive arms of the spiral differs on the different polytypes and is characteristic of the particular type, having a direct correspondence with the size of the $x$-ray unit cell. The step heights of these growth spirals have been found to be (I) equal to the size of the $x$-ray unit cell (2) a multiple (3) a fraction of the x-ray unit cell, giving the three types of spirals discussed in Chapters VII, VIll and IX respectively.

### 10.1. GROWTH SPIRAIS WITH EIEMENTARY BURGERS VECTOR

## (a) Si-C Crystals of Type 6H

The spirals belonging to the first type are the elementary spirals. By far the largest number of these growth spirals observed were on the commonest variety of Si-C crystals of type 6H. Since the step height of these spirals is equal to 15A, it is too small to be measured directly by the shift
of the individual Fizeau fringes at these steps, and, therefore, the methods outlined in Secs. 6.2 to 6.5 for finding the average step heights were utilized. The results of interferometric measurements are summarised below.

The growth spiral of fig. (18b) was observed on a crystal which was quite well developed. By measuring the interfacial angles between the basal plane and other faces, by a one circle goniometer available in the laboratory, it was found that these angles given in Table VI, agree within experimental errors with the data given by Thibault (19 $/ 4$ ) for type 6 H and, therefore, this crystal was identified to be of type 6 H .
Table (VI)


124 .

Three different methods given in Secs. (6.2a), (6.3), and (6.4) were applied for the measurement of step heights. Fig: (18a) shows Fizeau fringes under high dispersion passing over the peak of the spiral hill. That the Fizeau fringe is passing exactly over the centre of the spiral can be seen in fig. (18a), where the spiral turns have been revealed by the effect of diffraction (see Sec. 6.6). By knowing the angle through which ${ }_{h}^{\text {the }}$ izeau fringe bends at the centre, the dispersion i.e. the separation between the successive orders from fig. (18a), and 'd' the sepanation between the successive steps (changed to the same magnification as fig. (18a) ) from fig. (18b), the step height has been measured using equation (20). The result is given in column I of Table(VII). Fig (18c) shows the fringes of equal chromatic order corresponding to fig. (18a), and using equations (298(30), the measured step height is given in colum II of Table (VII). In column III is given the average step height by knowing the total difference in the level of the crystal on either side of the discontinuity line at a point $A$ and then dividing this by the difference in number of steps crossed in reaching this point from the centre of the spiral by going round the 'fish' like obstruction in a clockwise or anticlockwise direction.

| h, the measured step height for the growth spiral <br> in fig. (18a) observed on a crystal of type 6 H |  |  |
| :---: | :---: | :---: |
| Use of fizeau <br> fringes | Use of fringes of <br> equal <br> chromatic order | By counting the |
| $15.2 \mathrm{~A} ; 14.1 \mathrm{~A}$ | 17.1 A | steps |

A similar measurement of step-height was done for the growth spiral at the bottom of fig. (44), by the use of Fizeau fringes. The sesult of four independent trials for the measurement of step-height was:

$$
14.5 \mathrm{~A} ; \quad 15.5 \mathrm{~A} ; \quad 15.0 \mathrm{~A} ; \quad 15.3 \mathrm{~A} .
$$

These measurements show that the average step height of these growth spirals is 15.2 A with a maximum uncertainty of about lA. The lattice parameter ' $c$ ' for type 6 H is equal to 15.079 A (See Table (II) ). This shows that within the limits of experimental accuracy, the step height is equal to the lattice parameter $c$ of the X-ray unit cell. This is to be expected, since for the spirals observed on the basal plane (0001), the step height should be equal to the repeat distance along the 'c' - axis.

## (b) Si-C Crystals of Type 15R

The type of crystal studied next was the second most common variety of Si-C crystal of type l5R. The growth spiral observed on this crystal is illustrated in figs. (19a) and (34). The type of the crystal was again identified goniometrically and the interfacial angles between the basal plane and other faces are given in Table (VIII) below, and are compared with the data given by Thibault (1944).

Table (VIII).


This crystal had only three well-developed faces, besides the basal plane, suitable for goniometry. However, the measured angles $47^{\circ} 15^{\prime}$ and $63^{\circ} 45^{\prime}$ show it to be conclusively of type 15R, since these two angles do not occur for type 6 H and occur only for type 15 R .

The growth spiral observed on this crystal has straight edges (except at the centre) and therefore for the measurement of step height, by the application of Fizeau fringes, shown in fig. (19b) equation (26) was used. For greater accuracy, as discussed in Sec. (6.5), figures (19a) and (19b) were superimposed over one another as shown in fig. (19c). The results of the measurement of step height is given in Table (IX).

Table (IX)


This result of measurement shows that the step height is equal to $a_{\uparrow h}$, the size of the actual rhombohedral unit cell, which is equal to $\frac{1}{3}$ the length of the ' $c$ '- axis referred to the hexagonal axes. This is in accordance with the true stacking sequence, which for type 15 R is in Zhdanov's notation (32) or in Frank's notation $(\Delta \Delta \Delta \nabla \nabla)$.
(c) Si-C Crystal of Type 33R.

This interesting result needed some further confirma tion. To verify this, the type of a large number of crystals showing growth spirals was determined amongst Which one crystal which was determined to be of type 33R was found. Since the measurement of step height on this crystal wa s crucial, the type of this crystal was debermined accurately with the goniometer. Fortunately, this crystal had a number of faces quite well developed giving excellent reflections. In Table (X) the results of the measurement of the interfacial angles between the basal plane and the successive faces are reproduced and are compared with the data given by Ramsdell (1945).

Table (X)

| Angle between the basal plane and form |  | Quality | Form |
| :---: | :---: | :---: | :---: |
| Experimentally determined value with possible error | ${\underset{\text { Rata }}{ }}_{\text {Ramsdell's }}$ |  |  |
| $53^{\circ} 37^{\prime} \pm 2^{\prime}$ | $\begin{array}{lll}53^{\circ} & 321 \\ 53^{\circ} & 391\end{array}$ | A | $\begin{array}{ll} \frac{B}{B} & 0.1 . \bar{T} .23 . \\ 1.0 .1 & 23 . \end{array}$ |
| $61^{\circ} 26^{\prime} \pm 2^{\prime}$ | $\left.\begin{array}{lll} 61^{\circ} & 222_{2}^{1} \\ 61^{0} & 24^{1} & 1 \end{array}\right)$ | A | $\begin{array}{ll} W & 0.1 . T .17 . \\ W & 1.0 .1 .17 \end{array}$ |
| $70^{\circ} 41^{\prime} \pm 2^{\prime}$ | $\left.\begin{array}{ll} 70^{\circ} & 34 \\ 70^{\circ} & 33 \frac{1}{2} 1 \end{array}\right)$ | A | $\begin{array}{ll} \frac{x}{x} & 0.1 \cdot T .11 . \\ 1.0 . \frac{T}{11} .11 \end{array}$ |
| $75^{\circ} 48^{\prime} \pm 5^{\prime}$ | -- | B, thin | - - - |
| $81^{\circ} \quad 1^{\prime} \pm 2^{\prime}$ | $\left.\begin{array}{ll} 80^{\circ} & 53 \frac{1}{1} \\ 80^{\circ} & 52 \\ 2 \end{array}\right)$ | B, very thin face | $\frac{v}{v} 1.1 . \frac{1}{1} \cdot 5 .$ |
| $54^{\circ} 54{ }^{\prime}$ | - - | - | - - - - - |
| $62^{\circ} 4.71$ | $\begin{aligned} & \left.62^{\circ} 40 \frac{7^{\prime}}{}{ }^{\prime}\right) \\ & \left.62^{\circ} 46 \frac{1}{2} 1\right) \end{aligned}$ | A | $\frac{u}{u} \frac{1.0 . T}{0.16} \cdot \frac{16}{1.16 .}$ |
| $67^{\circ} 191$ | $\left.\begin{array}{l}67^{\circ} \frac{171}{1} 7^{\circ} \frac{1}{24},\end{array}\right)$ | B | $\begin{array}{ll} \frac{t}{t} & 1.0 .1 .13 \\ 0.1 .1 .13 . \end{array}$ |
| Two very thin faces | not measurable | - | --- - |
| $9005^{1}$ | - - - | - | - - - - - |
| $79^{\circ} 48^{1}$ | --- | - | --- - - |

This close agreement between the experimentally measured interfacial angles and the data given by Ramsdell was taken to prove conclusively that the crystal was of type 33R.

The growth spiral ooserved on this crystal is shown in fig. (101) or (75). The behaviour of the growth fronts and the resulting shape of the spiral have already been commented upon in Sec. (8.2). Fizeau fringes passing over this spiral are shown in fig. (l02). In accordance with the method of Sec. 6.5 for greater accuracy, Fizeau fringes are shown superimpos ed over the growth spiral in fig. (IO3). Since it is a polygonal spiral, again using the Formula (26) the step height was determined, the results of which are summarised in Table (XI).

Table (XI)

| Ramsdell's <br> Notation | Zhdanov and Frank's <br> Notations | Latice parameter <br> $c$ | Measured <br> step height |  |
| :--- | :---: | :---: | :---: | :---: |
| 33 R | (33 32$)$ | 82.94 A | 27.704 A | 27.8 A |
|  | $(\Delta \Delta \Delta \nabla \nabla \nabla \Delta \Delta \Delta \nabla \nabla)$ |  | 23.0 A |  |
|  |  |  | 28.3 A |  |

The measurement within limits of experimental accuracy shows conclusively that the step height for type 33R crystal is equal to $a_{\text {rh }}$ of the actual rhombohedral unit cell which is equal to $\frac{1}{3}$ its length along the $c$ - axis referred to the hexagonal axis.

Thus it seems reasonably established that in siliconcarbide crystals the step heights for elementary spirals on 131.
the hexagonal crystals is equal to the lattice parameter 'c' and in rhombohedral crystals the step height is equal to $a_{r h}$ of the rhombohedral unit cell, which corresponds to the actual stacking arrangement. Thus in both the cases so far studied, the step height is equal to the size of the actual X-ray unit cell. Such spirals, therefore, originate from dislocations with unit Burgers vector i.e. these are the elementary spirals.

In another crystal, the growth spiral on which is illustrated in fig. (16b), it has been possible to measure the step height by the shift of the Fizeau fringes (fig.16a) on these individual steps. The step height is equal to 130 A . Taking the step height $h=a_{\text {rh }}$, this crystal should be of type 159 R with Zhdanov symbol $\left[(33)_{8} 32\right]$. However, to confirm this prediction X-ray diffraction data would be needed.

### 10.2. GROWTH SPIRAIS ORIGINATING FROM DISLOCATIONS OF

## MUITIPIE STRENGTH

Often the growth spirals observed on silicon-carbide crystals having a high visibility, belong to this class. A typical example of such a spiral is shown in fig. (10) $)$, which is a part of fig. (70). Fizeau fringes passing on these spiral steps are shown in fig. (105). For photograping these Fizeau fringes a lightly silvered glass flat was used with the advantage that the spiral turns are visible simultaneously with the Fizeau fringes. The step height as measured by the

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shift of Fizeau fringes at these steps is equal to 620 A . The crystal was identified by usual goniometric measurements to be of type 6 H . The step height, therefore, is a multiple of the X-ray unit cell. This conclusion is further supported by the observation that these steps dissociate into component steps as shown in fig. (71).

Fig. (106) or (40) which shows the case of two screw dislocations of opposite hand generating closed loops is of interest. The shift of the Fizaau fringes (see fig. (107)) passing over these steps, gives the step height or the thickness of each layer $=120 \mathrm{~A}$. Since the ledges originating from the two screw dislocations fuse with one another without marking out a fault suface, it may be concluded that the steps originating from the two dislocations are identical and therefore the two dislocations have the same structure and strength. Since it is improbable that both these dislocations are the same multiple of a dislocation with a smaller Burgers vector, it may be concluded that the two dislocations are elementary dislocations and the crystal is a polytype with a large unit cell. If indeed the step height is equal to the $a_{r h}$ of the rhombohedral types, the crystal will be a polytype 1)I R with Zhdanov symbol $[(33), 32]$.

### 10.3. INTERPRETATION OF POLYMYPISM

These observations on growth spirals lead readily to an understanding of polytypism as observed on silicon-
carbide crystals, in terms of dislocations. The above interferometric studies have shown that the step height of the growth spiral is characteristic of the type of crystal on which it is observed, and is equal to the size of the $X$-ray unit cell. According to Burton, Cabrera and Frank's theory, the spiral form is obtained, when during the process of growth, the initial ledge formed on the face of the crystal by the emergence of the screw dislocation, winds itself into that shape. Thus the crystal growing by the presence of dislocations, is not composed of an indefinite number of layers siacked upon each other as ideally considered, but of a finite number of interleaved helicoids. Each helicoid axis is a dislocation. The structure necessarily repeats with a period corresponding to the pitch of the screw. Thus the step height will be equal to the height of the initial ledge. The step heights have already been shown to be equal to the size of the X-ray unit cell, which therefore becomes the crystal building unit giving rise to the different polytypes.

It, therefore, remains to explain the creation of the initial ledge. Frank (1951a)suggests that silicon-carbide crystals may initially grow into plates by surface nucleation mechanism. These plates will become self stressed, through non-uniform distribution of impurities or thermal stresses due to partially screened intense radiation, ultimately upto its theoritical yield stress, when the thin plate will buckle and shear. This will raise terminated steps on the crystal

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134 .
$$

face, and if the shear is by a uniform amount terminating fairly abruptly a ledge will be exposed. The crystal subsequently growing will have necessarily the structure corresponding to that of the ledge. So if the original crystal has a simple initial structure like that of type 6 H , with

Zhdanov symbol (33), and the slip is an integral multiple of the repetition period of this structure, the crystal growing will be of type 6 H . If, however, the slip is by a non-integral multiple of this period, the resulting structure will be a polytype. This will explain the structure with Zhdanov symbol [(33) n 32]. Since a non-integral slip will leave a misfit on the slipped surface, it should be less common than the integral slip. This explanation, however, does not explain the non-occurrence of structures with Zhdanov symbol $\left[(33)_{\text {n }} 31\right]$, $\left[(33)_{\mathrm{n}} 35\right]$ etc.

Vand (1951) has also given an explanation on similar lines. An alternative explanation for polytypism is possible. If the initial structure contains a stacking fault in the region whose ledge becomes exposed, we will get a polytype with period equal to the step height.

Whatever be the cause of intitial ledge, the $X-r a y$ unit cell forms the crystal building unit giving rise to the different polytypes.

## CONCLUSIONS

## PRESENT POSITION OF EXPERIIGNTAL OBSERVATIONS.

### 11.1. CONTRIBUTIONS BY THE PRESENT IIVESTIGATIONS

As stated in Chapter III, when the present investigation was started the only experimental evidence available in support of the spiral mechanism of crystal-growth due to the presence of dislocations, were the observations by Griffin (1950) on beryl crystals. These observations were meagre and qualitative. Because of the small number of turns which the spiral was developed (only two turns) it was not possible to make any measurements on the spiral itself. It was shown that the step height at the 'line markings' was less than 34 A i.e. less than 4 unit cells. It could only be inferred that these features are growth features in accordance with the theory.

In the present investigation, using improved experimental techniques, numerous growth spirals have been observed and many of the theoretical predictions have been confimmed and new experimental facts and data have been obtained which have supplemented the theory and lead to the understanding of new facts.

The theory of crystal growth as developed by Burton,

Cabrera and Frank (1951) predicted tha t the crystals growing by the presence of screw dislocations will exhibit on their faces flat spiral growith pyramids, the step heights being "monomolecular", the exact shape and step height being left as an unsettled question. The present investigations soon revealed that these spirals could be classified into three types. Firstly, elementary growth spirals originating from screw dislocations with unit Burgers vector. Secondly, growth spirals originating from screw dislocations of multiple strength. Thirdly, interlaced growth spirals. The last two types had not been anticipated by theory. Further, the idea of unit Burgers vector needed clarification. The growth spirals were said to be "monomolecular" which is by no means the case. It is the $X$-ray unit cell that acts as the crystal building unit which forms the step height. Those spirals which have a step height equal to the $X$-ray unit cell are called the spirals originating from dislocations with unit Burgers vector. It should be made clear, that even in such a spiral the step height is equal to several molecular thicknesses e.g. for type II or 6 H , the step height is equal to 15 A which is equal to 6 molecular layers.

The spirals, whose step heights were determined to be equal to a multiple of the X-ray unit cell showed that it is possible for dislocations to be of multiple strength and, therefore, for defining a dislocation in any material, the strength or Burgers vector has to be specified.

The third type of spiral viz: the interlaced spirals were entirely new. It demonstrated that under certain conditions of growth, step heights could also be a fraction of the unit cell in certain parts of the growth spiral. Further it demonstrated the variation of the dependence of growth rate on the crystal surface in different orientations.

In addition, the microscopic observations gave information about the shape of the spirals. For the first time it was demonstrated by the growth spirals observed on silicon-carbide crystals that the same crystal could exhibit both circular and polygonal spirals (regular hexagonal) and also intermediate cases. This has not yet been opserved in any other study - nearly in all observed cases the spirals are polygonal.

Besides giving information about the shapes of the spirals, microscopic observations have illustrated the different properties of growth fronts; the interaction of growth fronts originating from different sources on the same crystal face and the fault surfaces produced. This leads to the explanation of the complex growth patteins when 2, 3 or larger number of screw dislocations emerge on the crystal face. The curves of intersections when the series of growth fronts meet eqch other and several complex geometrical patterns resulting from groups of dislocations arranged in different ways have been illustrated. When a very large
number of dislocations emerge on the crystal certain
statistical properties like density of dislocations have been studied. A significant observation is that it is characteristic that in any one region of the crystal, the dislocations are predominantly of the same sign and have the same strength.

Experimentally pairs of dislocations of opposite sign are seldom observed. Amongst all such pairs observed so far on silicon-carbide, a pair of dislocations close to each other and equally developed has not been observed for dislocations of elementary Burgers vector with small step heights. However, such a rare case was observed for dislocations giving rise to step heights 120 A . This observation could be explained that in addition to the attractive forces between the two dislocations of opposite sign, there must be a constraining force trying to anchor these dislocations to their equilibrium positions between the lattice rows. This observation leads to the conclusion that this constraining force which was taken by Peierls (1940) and Nabarro (1947) to depend upon elastic constants only depends upon the strength of the dislocation, so that the attractive and the anchoring forces can balance each other at a certain distance of soparation between the dislocations.

The step heights have been measured accurately by the application of multiple-beam interferometry. It is
found that the step heights of the growth spirals observed on the different types have a direct correspondence with the X-ray unit cell. This leads to the understanding of the interesting property of polytypism as observed on siliconcarbide crystals, in terms of dislocations.

### 11.2. PRESENT POSITION OF OBSERVATIONS

The volume of experimental observations in support of the theory of spiral mechanism of crystal growth has grown considerably in the interim period, and a brief description in the chronological order will be given.

Dawson and Vand (1951) using electron microscopic techniques have observed the growth spirals of long-chain paraffin crystals $\left(C_{36} H_{74}\right)$. These spirals are rectangular in shape. By metal shadow casting they have show the step height to be equal to $47 \pm 5 \mathrm{~A}$, which, within experimental errors is equal to the size of the X-ray unit cell.

The growth of cadmium-iodide from aqueous solution was first studied by Bunn and Emmett (1949) to study the layer formation. The spiral mechanism of growth of cadmiumiodide crystals was demonstrated by Forty (1951, 1952). The step heights of the growth spirals on cadmium-iodide crystals are not of molecular thicknesses, but are several hundred angstrom units high. Many growth patterns on cadmium-iodide were found to have marked resemblance with the growth patterns

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I_{4} 0
$$

observed on silicon-carbide crystals, and it is concluded that cadmium-iodide also exhibits polytypism similar to that observed on silicon-carbide.

Haematite $\left(\mathrm{Fe}_{2} \mathrm{O}_{3}\right)$ crystals also show growth spiral features (Verma 1952). Both polygonal and curvilinear spirals were observed. By the application of the multiplebeam interference fringes, step heights have been measured and shown to be equal to the value of the repeat distance predicted by X-ray phenomenon.

Triangular spiral features have been observed by Amelinckx (1952) on chemically deposited gold and from their visibility it is inferred that the step heights are large. Spiral features have also been observed by Forty (1952 ) on magnesium formed in a furnace. No measurements of step heights have been reported. From the visibility it is inferred that these originate from dislocations of small Burgers vector. Amelinckx (1952a)also reports a spinal formation on mica.

These are the observations reported up-to-date. However, it is thought that a number of crystals will demonstrate this spiral mechanism of growth, the observations on which may be awaited.

## 1)1.

### 11.3. COMPARISON OF THE OBSERVATIONS ON SI-C WITH OTHER

## OBSERVATIONS

The observations on silicon-carbide crystals are unique. No other crystal has yet been observed to exhibit a.ll the three types of growth spirals viz: growth spirals originating from dislocations of unit Burgers vector, growth spirals originating from dislocations of multiple strength, and interlaced spirals. The only other crystal observed to exhibit the interlaced spiral is cadmium-iodide.

The measurement of step heights of elementary growth spirals has been done on only a few crystals. The available data of step heights on long-chain paraffin crystals (Dawson and Vand 1951) and on haematite (Verma 1952) show that the step heights are equal to the predicted $X-r a y$ values. The large step heights on cadmium-iodide crystals (Forty 1952) have been shown to be large integral multiples of the smallest repeat unit.

A noteworthy point in the spirals on Si-C crystals is that the centre of the spirals is marked visibly by a hole, the size of which is observed to vary. (Compare fig. (22) with (35) etc.). According to Frank (I951b), a dislocation of Burgers vector exceeding about 10 A will be in equilibrium only with an empty tube at its core so that there will be a. hollow at the point of mergence of the dislocation on the crystal sufface. However, in the growth spirals observed on

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1)_{4} \text {. }
$$

paraffins which have a step height of 47 A , the points of emergence of dislocations are not marked by a hole. This may be attributed to the dissociation of a complete dislocation into weak partial dislocations. It is interesting to note that the point of emergence of dislocation in haematite crystals of step heights nearly 14 A is not marked by a hole.

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My thanks are due to all my colleagues for their constant assistance and to the laboratory staff for all their help.

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# Observations on Carborundum of Growth Spirals Originating from Screw Dislocations. 

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[Plates XXV.-XXVIII.]

## Abstract.

Numerous growth spirals with shapes ranging from circular to regular hexagonal have been observed on carboṛundum crystals of types I. and II., by coating the crystal faces with a thin film of silver of reflectivity nearly 90 per cent and then working in reflection, using phase contrast illumination. The shapes of these spirals, in relation to the crystal structure, are shown to be in accordance with the predictions of Frank's theory. On a type II. crystal, hexagonal interlaced spirals have been observed. The annihilation of growth fronts where they meet, and other properties of growth fronts are illustrated and hence the observed patterns for two or more screw dislocations are explained. The observed density of dislocations ranges from small values up to a maximum of $10^{4}$ per sq. cm. For a typical circular spiral the calculated values of the radius of the critical nucleus is $2 \mu$ and supersaturation is $0 \cdot 2$ per cent. By the application of multiple-beam interference, using both Fizeau fringes and fringes of equal chromatic order, the step heights in spirals have been measured accurately for type II. crystal and found to be $15 \AA$. This is equal to the height of the unit cell, proving that these are growth spirals originating from screw dislocations, in exact accordance with theoretical prediction.

## §1. Introduction.

According to Burton, Cabrera and Frank (1949) growth of crystals at low supersaturations can take place only in the presence of dislocations. A crystal should, therefore, have a number of dislocations with a screw component terminating on the crystal face. Frank (1949) showed that when growth takes place on the molecular terraces so exposed, the edges of monomolecular layers develop as "growth spirals" centred on the dislocation. Experimental evidence supporting this was found on beryl by Griffin (1950). The present paper deals with dislocations and "growth spirals " found on the faces of carborundum crystals.

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## §2. The Crystal Structure and Types of Carborundum.

Carborundum, a strongly homopolar crystal, occurs in at least eight known types. One of these is cubic, sometimes called $\beta$-Sic. All other types ( $\alpha-\mathrm{SiC}$ ) are based on either hexagonal or rhombohedral unit cells. All types have identical layers, but differ in their arrangements. Each type is distinguished by the number of layers in the unit cell. The basal pinacoid is predominantly developed, and it is on this that these growth spirals have been observed.

The crystals studied were either pale green, dark green or black. Some, which have a few well developed faces, have had their structural types determined by a goniometric method (Thibault 1944). X-ray diffraction methods will be required for the others.

No cubic crystal has been studied. Most of the crystals examined were of the commonest type, carborundum II. Its unit cell is hexagonal with six layers, and in Ramsdell's notation is 6 H (Ramsdell 1947). The lattice parameters are

$$
a=3.073 \AA, \quad c=15.079 \AA .
$$

In this work the only other type available was carborundum I. This has a rhombohedral unit cell and referred to the hexagonal axes consists of fifteen layers. In Ramsdell's notation it is 15 R with

$$
a=3.073 \AA, \quad c=37.70 \AA .
$$

## §3. Visibility of Growth Spirals.

Numerous " growth spirals" have been observed on the faces of carborundum (SiC) crystals. These spirals are well developed; over thirty turns of the spiral can be traced in some cases. The spirals are centred on a dot which must mark the point of emergence of a screw dislocation on the crystal face.

The clean surface of the crystal when examined by a metallurgical microscope, using bright field illumination, does not show up these features, the surface appearing smooth. A little amount of impurity makes these features slightly visible (fig. 8, PI. XXVI. has been taken by this method). Breathing lightly on the crystal face, while it is under observation, increases the visibility and the " lines " flash out, but soon disappear when the water re-evaporates. The " lines" seen by breathing are dotted and slightly diffuse, but the visibility obtained by this method is high. Though convenient for visual observations, the procedure is not suitable for photography.

Following Griffin's technique, contrast was increased by deposition of a thin film of silver on the crystal face using thermal evaporation. This was improved by the use of phase contrast illumination. The photographs have been taken using positive phase contrast, the absorption of the phase plate being 80 per cent and phase retardation equal to $\frac{1}{2} \pi$. With this equipment many features are often still faint and only

## Spiral Growth on Carborundum Crystal Faces

In 1949 Frank $^{1,2}$ pointed out the possibility that growth of crystals at low supersaturations, essential for good crystals, could take place because of the formation of dislocations in the crystal so that any real crystal should have a number of dislocations with a screw component, terminating on the face. When growth takes place on these exposed molecular terraces, the edges of these layers develop into spirals centred on the dislocation.

Griffin ${ }^{3}$ has observed these 'monomolecular' layers on the ( $10 \overline{1} 0$ ) face of a beryl crystal, and has shown by multiple-beam interferometry that the height of these steps is less than 34 A ., that is, less than four unit cells of the crystal. It was inferred that these steps are only one unit cell high.

In the present investigation, numerous 'growth spirals' have been observed on the faces of carborundum and measured with the aid of phase-contrast microscopy and multiple-beam interferometry.

Carborundum ${ }^{4}$ occurs in at least eight known types, one of which is cubic, whereas the rest are either hexagonal or rhombohedral and have identical layers but differ in their arrangement and are uniquely distinguished by the number of layers in the unit cell. The crystals studied here are of type I (rhombohedral, fifteen layers, with lattice parameter $c=$ $37 \cdot 7 \mathrm{~A}$.), and type $\Pi$ (hexagonal, six layers, $c=$ $15 \cdot 1 \mathrm{~A}$.).

These spirals were studied by coating the crystal faces with a thin film of silver of reflectivity nearly 90 per cent, deposited by thermal evaporation, and then examining these faces in reflexion.

Theory shows that for growth taking place from vapour, the ledge extending from the point of emergence of the dislocation to the crystal boundary has a rate of advance independent of the crystallographic orientation, thus forming a simple Archimedean spiral which can be calculated and from which the constant of spacing between turns can be predicted. These predictions have been completely confirmed numerically by the circular spirals shown in Fig. 1.

The dependence of the rate of advance of a growth front on the orientation of the step line should impose a characteristic distortion of the growth of spirals, exhibiting the crystal symmetry. In accordance with this, Fig. 2 shows a hexagonal spiral (crystal type II). The straight edges correspond to a sharp minimum in the growth-rate as a function of orjentation.

The complex growth patterns predicted for two or more screw dislocations ending on a crystal face and depending on the property of growth fronts which annihilate each other where the two edges meet are illustrated in Fig. 1. Thus for two screw dislocations of opposite hand, with the unfolding of the two spirals the ledges starting from one terminate on the 'other, generating closed loops.

Various other growth patterns for two, three and larger numbers of dislocations ending on crystal faces of type I and type II have been photographed and explained.

Interlacing of hexagonal spirals observed on a crystal face of type II is illustrated in Fig. 3.

The observed density of dislocations varies widely on different specimens, ranging from a few to a maxi-

mum of $\sim 10^{4}$ per sq. cm. On any crystal they are predominantly of one hand.

The calculated radius of the critical nucleus is $2 \mu$ and the supersaturation 0.2 per cent.

To measure the step height of these spirals, multiplebeam interference (Tolansky ${ }^{5}$ ) has been employed. Fig. 4 shows the Fizeau fringes for $\lambda 5,461$, passing over a circular spiral, in which the height can be accurately measured; and as the number of turns is readily visible, the height of each single step can be deduced with precision. Analogous measurements
have been made also with fringes of equal chromatic order. The step heights on a type II crystal measured from two different spirals are respectively $15 \cdot 2 \mathrm{~A}$. and $15 \cdot 1 \mathrm{~A}$., with a maximum uncertainty of 2 A . It is already known from X-ray analysis that, for type II, $c=15 \cdot 1 \mathrm{~A}$. Thus it has been proved here that the step is a single unit-cell high.

The observation of spiral markings on carborundum has already been reported ${ }^{6}$. The observed shapes of these spirals are in accordance with the predictions of theory, and their step height is equal to that of a unit cell, showing that these are growth spirals originating from screw dislocations.
A more detailed account of this work has been communicated elsewhere. I am grateful to Prof. S. Tolansky for his interest and encouragement in the course of this work, and to the British Council for the award of a scholarship.

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just visible. Usual photographic methods for increasing the contrast have been employed in some of the photographs given.

In fig. 13 (Pl. XXVIII.), it is seen that the visibility and contrast is high compared with other photographs. The surface of this crystal was not very clean when it was silvered. The silver deposit was not uniform, the surface appearing mottled. Examination with phase contrast illumination gave high visibility. This suggests that impurity can make the steps more visible.

## §4. Shape of the Spiral for a Single Screw Dislocation.

The growth spiral will have a shape depending upon the rate of advance of a growth front in different crystallographic directions.

For growth taking place in accordance with Frank's ideas two cases arise :-
(a) when the Frenkel kinks on the step (exchange sites) are close together and the distance moved by an adsorbed molecule before it hits a step is large ;
(b) when the kinks are few or the distance moved by the adsorbed molecule is small.
When the former conditions exist, which are more likely to occur in growth from vapour, the molecule will have a high probability of adhering to the step if adsorbed near it, irrespective of the crystallographic orientation of the step. Thus for growth from the vapour, taking the rate of advance of the ledge to be independent of direction, the ledge will form a simple spiral under steady uniform supersaturation. The form of the spiral can be represented by the Archimedian equation

$$
r=2 \rho_{c} \theta,
$$

and the constant spacing between turns is

$$
\delta r=4 \pi \rho_{c},
$$

where $\rho_{c}$ is the radius of critical nucleus, equal to $a \phi / 2 k \mathrm{~T} \ln \alpha$, and where $\alpha$ is the supersaturation ratio, $a$ is the interatomic distance and $\phi$ is the neighbour-neighbour binding energy of the crystal.

These predictions are confirmed by the circular spirals shown in figs. 1, 2, 3 and 8 (Pls. XXV., XXVI.). It is to be noted, however, that the spiral turns are more closely spaced at the centre, and the spacing gradually increases on going away from the centre until it becomes nearly constant. This is in accordance with the prediction of theory (Burton, Cabrera and Frank 1951).

Any dependence of the rate of advance of a growth front on the orientation of the step-line could impose a distortion of the growth spir.als, so that they exhibit the symmetry of the erystal face. Such an effect has been found in fig. 4 (Pl. XXVI.), where the spiral is nearly circular at the centre, and gradually takes on the hexagonal symmetry of the
crystal face (carborundum type II.). In fig. 7 (Pl. XXVI.) is a hexagonal spiral observed on a crystal identified to be of type $\Pi$. This is a regular hexagonal spiral, showing clearly the dependence of the growth rate on the crystallographic orientation. The step-lines very near the centre show a curvature, which, as predicted by theory, decreases with distance from the centre. However, soon the straight step-lines start rounding off at the corners and become gradually curved on moving away from the centre. These step-lines do not meet the line of discontinuity sharply, but tend to curve away from it, as shown in fig. 7, for the outer five or six step-lines.

The straight edges show that under certain conditions there is a sharp minimum in the growth rate as a function of orientation.

In figs. 10 and 11 (PI. XXVII.) further spirals are shown. Fig. 10 has been observed on a rhombohedral crystal type I.

## §5. Properties and Behaviour of Growth Fronts.

The growth pattern for two or more screw dislocations ending on a face is complex and depends on the properties of the growth fronts. The growth fronts starting from a single screw dislocation will spread on the surface of the crystal face in regular shapes, but the presence of a boundary or an obstruction will distort its regular shape. When the advancing growth fronts meet an obstruction they can propagate round corners, as shown at the upper end of the obstruction in fig. 4 ; this point behaves almost as a source of secondary growth fronts.
The growth fronts emitted by two sources of opposite sign annihilate each other where they meet. Numerous examples of this can be seen in figs. 2 and 3 (PI. XXV.). When there are several screw dislocations actively emitting growth fronts, a point on the crystal face will be in the dominant field of only one of these, and this alone determines the number of growth fronts passing through it. This is exemplified in fig. 2 where there are five screw dislocations. By choosing the point of observation, say, near the bottom screw dislocation, the number of growth fronts passing through it is solely determined as if this alone were active.

## §6. Growth Spirals for Two or More Screw Dislocations.

In fig. 17 is drawn schematically the growth pattern for two screw dislocations A and B of the same hand. The ledge starting from A goes on rotating and generating the spiral until it meets at $p_{1}$ the ledge originating from B where it terminates. At $p_{1}$ the two ledges fuse with one another. As the spirals unfold themselves the ledges meet at $p_{1}, p_{3}, p_{5} \ldots$ in the upper half and at $p_{2}, p_{4}, p_{6} \ldots$ in the lower half of the figure. The locus of points of intersection for two equal spirals has been shown to be a cartesian oval (Burton, Cabrera and Frank 1951). Between $p_{1}$ and $p_{2}\left(p_{3}, p_{4}\right)$, etc., the missing parts of the two spirals are shown by the dotted lines. The resultant figure is the solid line curve.

Starting from A and going round the spiral we descend by one step in each complete turn till we come to the point $p_{1}$. From $p_{1}$ we go round the spiral B to the point $p_{4}$ and then again on the spiral A to the point $p_{5}$. Thus in going round the resultant curve once, we descend by two steps from $p_{1}$ to $p_{5}$ to $p_{9}$ and so on. Similarly, starting from B and going round we will descend by two steps, from $p_{2}$ to $p_{6}$, etc. . . . As the curves gradually smooth out at the points of contact, the figure will appear to be two spirals alternately spaced. Fig. 17 has been drawn for circular spirals, and the case for spirals with straight edges can similarly be drawn where the behaviour will be the same. In fig. 3 (Pl. XXV.) the case for circular spirals is illustrated.

Fig. 17.


Fig. 8 (Pl. XXVI.) illustrates a unique example in which the spiral is doubled with the members strictly "parallel ". It may be that the twin form arises from two close-by dislocations of the same sign, cooperating closely.

In fig. 9 (Pl. XXVII.) is illustrated the case of two screw dislocations of the same sign close to each other. The spirals are circular and developed for two or three turns after which the ledges from other neighbouring dislocations interact with them.

In fig. 10 (Pl. XXVII) is shown another case of two similar screw dislocations close to each other, so that growth starts from both of them. The spirals are circular at the centre for one or two turns after which they settle down as spirals with straight edges. The meeting of the growth fronts
from the two screw dislocations results in small kinks in the innermost straight edges. As in the case of circular spirals, here also by going round we descend by two steps, and the figure has the appearance of two spirals alternately spaced. However, the step height between successive lines in any particular direction is just one unit.

Fig. 11 (Pl. XXVII ) shows the case in which the central screw dislocation has developed several turns before reaching the point where the second small screw dislocation emerges. They quickly accommodate each other and the behaviour is similar to the previous cases. The central screw dislocation is dominant and would determine the rate of crystal growth of the face. Near the edge of the figure it is seen that some more screw dislocations emerge on the crystal face, and are situated in the same direction from the central screw dislocation as the second one. These new screw dislocations yield within a short while to the domination of the central one and quickly fall in line, passing on the growth fronts with slight delay and in slightly modified form.

Now consider two screw dislocations of opposite hand terminating on the crystal face. The ledge starting from one terminates on the other, and with the unfolding of the spirals the two arms join together generating closed loops. This is exemplified in fig. 3 (Pl. XXV.), where one of the spirals has developed several turns before the other starts growing.

The growth pattern for three screw dislocations of the same hand observed on a crystal of type $\Pi$. is illustrated in fig. 12 (PI. XXVII). Here, again, the spirals are circular at the centre and soon change into hexagonal spirals. It can easily be seen that, for three screw dislocations cooperating with each other, by following any one of the edges, the resultant curve descends three units in each turn. It should again be emphasized that the step height in the successive lines will be just one unit.

At the centre the ledges are closely spaced and, once they have settled down, the ledges are more widely spaced.

Fig. 2 (Pl. XXV.) illustrates the interaction of five screw dislocations. The growth fronts emitted by the screw dislocation at the top of the figure meet, first, the growth fronts advancing from the screw dislocation on the left of the figure and then, later, the growth fronts advancing from the bottom screw dislocation. Annihilation occurs over portions of the resultant growth fronts which assume characteristic shapes composed of ares of circles with these dislocation points as centre. Near the centre of the figure, due to the interaction of different growth fronts a crowding occurs. Here the compound growth fronts are not arcs of circles with the different dislocation points as centres, but instead there is a gradual change in curvature.

## §7. Hexagonal Interlaced Spiral.

These features observed on a crystal face of carborundum type II. are shown in figs. 13 and 15 (Pl. XXVIII). In each of these hexagonal spirals the edges fork out at the corners and meet the two neighbouring edges.

This interlacing gives the hexagonal spiral the " spider web" structure shown clearly in fig. 13 which shows the interlinking of four such spirals.

A double interlaced spiral is shown in fig. 14 (Pl. XXVIII.) in which the edges do not meet each other. The lines are broad with inner edges sharp and the outer diffuse.

An explanation of this interlacing has been given by Frank (1951).

## §8. Measurement of Step Height.

The step height has been measured by the use of multiple-beam interference fringes using both Fizeau fringes of equal thickness and the fringes of equal chromatic order (Tolansky 1948).

A rounded spiral, effectively a spiral conical hill, may be considered as a circular conical hill made of a series of concentric steps with a constant spacing $d$ and step height $h$. It can be shown that if a Fizeau fringe passing over the peak of such a hill appears to bend through an angle $2 \theta$, and if X is the dispersion, i.e. the distance between successive fringes, then the step height $h$ is given by

$$
h=d \lambda \sin \theta / 2 \mathrm{X} .
$$

By measuring X, $\theta$ and $d, h$ can be evaluated. Fig. 5 (Pl. XXVI.) shows the Fizeau fringes passing over the spiral of fig. 4 ( $\lambda 5461$ ).

For examination with fringes of equal chromatic order, the image of the peak of the hill is projected on to the spectrograph slit. This was arranged to prodce a system of fringes of equal chromatic order parallel to the spectrum line in one half of the field and sloping towards the red in the other (fig. 6, Pl. XXVI).

Since the step height is obtained from the mean of all those contributing to form the peak, irregularities of the optical flat and the lack in faithfulness of silver contouring are averaged out.

In one case another determination of the step height has been possible. In fig. 4 (Pl. XXVI ) starting from the centre of the spiral we can reach any point A on the line of discontinuity, either by going round the " fish-like" obstruction in a clockwise or an anti-clockwise direction. In the former, we encounter, say, $\mathrm{N}_{1}$ steps. Therefore the point A is $\mathrm{N}_{1}$ steps lower with respect to the centre of the spiral. In the latter case we go down, say, $\mathrm{N}_{2}$ steps from the peak of the hill in order to arrive at A. Thus at A the difference in level on the two sides of the line of discontinuity is that corresponding to $\left(\mathrm{N}_{2}-\mathrm{N}_{1}\right)$ step heights. This difference is quite large (over 50) and is therefore capable of being measured accurately and easily either by Fizeau or fringes of equal chromatic order. Knowing this, the step height has been evaluated, but is subject to uncertainty due to the possible presence of hidden dislocations in the obstacle and discontinuity surfaces.

## § 9. Result of Measurement of Step Height.

It is seen below that the step height measured in the cases so far is equal to just one unit cell.

| Fizeau fringes | Fringes of <br> equal chromatic <br> order | Method by <br> counting No. <br> of steps | Crystals |
| :--- | :---: | :---: | :---: |
| $15 \cdot 2 \AA$ | $17 \cdot 1 \AA$ | $14 \cdot 8 \AA$ | Spiral in <br> fig. 4, Type II. <br> $14 \cdot 1 \AA$ |
| $14 \cdot 5 \AA$ |  |  | Circular spiral, <br> right of fig. 2. |
| $15 \cdot 5 \AA$ |  |  |  |
| $15 \cdot 0 \AA$ |  |  |  |
| $15 \cdot 3 \AA$ |  |  |  |

§10. Discussion of Results.
From fig. 2 (Pl. XXV), which is at magnification $\times 90$, the spacing between the successive arms of the circular spiral when it is nearly constant is approximately 2.5 mm . Using $\delta r=4 \pi \rho_{c}$ we have

$$
\rho_{c}=\frac{2 \cdot 5}{90 \times 4 \pi} \mathrm{~mm} . \approx 2 \mu
$$

From $\rho_{c}=a \phi / 2 k \mathrm{~T} \ln \alpha$ and using Trouton's rule to estimate $\phi / k \mathrm{~T}$ according to which $\phi / k \mathrm{~T}=3 \cdot 5 \mathrm{~T} b / \mathrm{T}=6$ at an absolute temperature of 0.6 of the boiling point of the material we get

$$
\alpha \approx 0.2 \text { per cent. }
$$

§11. Density of Dislocations.
The density of dislocations varies widely on different specimens of carborundum. In fig. 4 (Pl. XXVI.) there is only one which dominates the growth of the face. In figs. 1, 2, 3, 11 and 12 (Pls. XXV., XXVII.) there are several. The largest density of dislocations observed is shown in fig. 16 (Pl. XXVIII ). Here there are nearly $10^{4}$ screw dislocations per square centimetre.

Another noteworthy point is that in fig. 16 (Pl. XXVIII.) there are nearly twenty screw dislocations, most of which are of the right-handed type. It is characteristic that in any one region there is a large predominance either of right-handed or of left-handed screw dislocations.

## §12. Summary.

Numerous growth spirals starting from points of smergence of screw dislocations have been photographed on the surfaces of carborundum crystals. These spirals have characteristic shapes. The shape is discussed in relation to the crystal structure. The behaviour and properties of

Fig. 2.

Fig. 1.

$\times 72$

Fig. 3.


Fig. 4.


Fig. 6.


Fig. 7.
Fig. 8


Fig. 9.


Fig. 11.

$\times 72$

Phil. Mag. Ser. 7, Vol. 42, PI. XXVII.

Fig. 10.


Fig. 12.


Fig. 13.


Fig. 15.

$\times 960$ nearly

Fig. 14.


Fig. 16.

growth fronts and the growth patterns for two and more screw dislocations are illustrated. From the observations on the photographs it is shown that the type of information that can be derived is the determination of the radius of the critical nucleus, the supersaturation and density of dislocations.

The step height has been measured accurately by multiple-beam interference fringes. The step height at the edges of these growth spirals is found to be one unit cell.

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[^1]
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Fig. 65. Group of dislocations giving a repeat pattern

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Fig. 75. A pair of spirals touching each other on one edge
p. 46

Fig. 76. A trigonal spiral with rounded corners
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## INTERFEROMETRIC STUDIES

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Schematic Description of a Crystal Surface.


Fig l. Crystal Surface at low temperatures.


Fig la. Surface at low
temperatures.


Fig 3. Surface with an island.


Fig 2. Surface at higher temperatures.


Fig 4. An edge dislocation.


Fig 5. The structure of an edge dislocation.


Fig 6.
Illustrating the formation of a screw dislocation.


Fig 9.
The structure of a screw dislocation.


Fig 8. End of a screw dislocation.


Fig l0. Development of a growth spiral.

## CRYSTAL STRUCTURE OF SiC.



Fig ll. Lattice of silicon-carbide
(a) modification 15 R. (b) modification 6 H . (c) modification 4 H.


Fig 12a. Symmetry elements in the projection on (0001) plane.


Fig 12b. Projection on (0001) plane.
A layer marked by o
B layer marked by $x$


Fig 13. (11 $\overline{2} 0)$ section showing zig-zag arrangement.

OPIICAL AND INTERFEROMETRIC ARRANGEMENT:

TECHNIQUES AND SOME APPLICATIONS
+hix


Fig ILa. Diagram of light path through a phase-contrast microscope.


Fig lLb. Light vectors.

S - Undeviated wave through the surrounding medium

P - through the particle
D - deviated wave

Plan view of phase plate


Fig I Lc. Optical system of the phase-contrast vertical-illumination microscope.


Fig 15. Optical arrangement for Fizeau fringes in the reflected system.


Fig $16 a$.
Showing shift of Fizeau
fringes pass-
ing over the
spiral steps
of fig 16 b .


Fig 16 b .
Hexagonal
spiral with
step height
130 A.


Fig 17a. Diagrammatic representation of a spiral conical hill as a circular conical hill and a Fizeau fringe passing over the peak.


Fig l7b. Fizeau fringe passing over a hill composed of a series of parallel steps.




Fig l9a. A double spiral with straight edges. (except at the centre).


Fig l9b. Fizeau fringes passing over the spiral steps of fig l9a.
12.


Fig 19c. Superposition of figs. I9a and l9b.


Fig 20. showing increase in the interferometer gap $\delta t=2 N h, N$ being the number of steps (each of height h) crossed.

THEIR INTERACTION

$\times 90$
Fig 2l. Circular spirals.


Fig 22. Regular hexagonal spiral.


Fig 23.

Spiral with
six rounded
edges.


Fig 24 .

Two hexagonal
spirals with
rounded edges.


Fig 25. Hexagonal spiral. At the centre several turns are rounded and closely
spaced.


Fig 26. illustrating the phenomenon of "domination"


Fig 27.
showing the
upper part
of fig 26.
$x 90$
17.


Fig 28.
Enlargement
of part of
fig 27.
$\times 150$

$\times 90$
Fig 29. Another example of the phenomena of "domination".


Fig 30. Two screw dislocations of the same sign at a distance $<P_{c}$, co-operating with each other.


Fig 31. Schematic representation of the resultant growth pattern, originating from two dislocations of the same sign at a distance $>P_{c}$.

Observed Growth Patterns For Two Screw

> Dislocations of the Same Sign.


Fig 32. Two left-handed dislocations at a distance $>\rho_{c}$.


Fig 33. Two right-handed dislocations at a distance $>P_{c}$; illustrating hyperbolic curve of intersection.


Fig 34. A pair of 'alternately spaced' hexagonal spirals with the central turns rounded observed on a crystal of type 15 R .


Fig 35. Circular growth spirals; left half illustrating the formation of closed loops (nearly circular) due to two dislocations of opposite sign.


Fig 36. Interaction of circular growth spirals and their curves of intersection; Note the lines of discontinuity running across the figure.

Two Screw Dislocations of Opposite Sign.


Fig 37. A ledge running between two dislocations of opposite sign ending on a crystal face.


Fig 38. Schematic representation of the formation of closed loops from a pair of unlike dislocations.


Fig 39. Schematic representation in three dimensions of several stages of growth from two dislocations of opposite sign.


Fig 40. Closed triangular and hexagonal loops from a pair of unlike dislocations.


Fig 4l. A pair of unlike dislocations of unequal strength forming closed loops with an edge running at the - points of contact.


Fig. 42. Closed hexagonal layers with no trace of dislocations at the centre.

$$
26
$$


$\times 550$
Fig 43. Three dislocations of like sign close together giving rise to three co-operating spirals. The central or the last part of growth spirals is circular, the rest being hexagonal.


Fig 44. Resultant growth pattern from five separated screw dislocations.


Fig 45. A group of six close dislocations.


Fig 44. Resultant growth pattern from five
separated screw dislocations.


Fig 45. A group of six close dislocations.


Fig 46. A number of circular growth spirals
originating from dislocations of the
same sign. Density of dislocation $\sim 10^{4} / \mathrm{cm}^{2}$.


Fig 47. Polygonal spirals originating from dislocations with density $\sim 10^{5} / \mathrm{cm}^{2}$, all of the same sign.


$$
\times 580
$$

Fig 48. Large number of polygonal spirals with a barrier
of dislocations.


## $\times 300$

Fig 49. Illustrating curve of intersection.


Fig 50.
Formation
OI closed
$\Delta$ loops
by growth
fronts from
three dis-
locations.
$\times 300$
32.


Fig 52. Upper half of the fig., illustrates the interaction of two circular spirals equally developed. The curve of intersection is a straight line perpendicular to the line joining the two dislocation points and passes through their middle point.


Fig 53.

$\times 900$
Fig 54. Growth steps terminating at points marked by a series of dots.

Fault Surfaces.


Fig 55.
$\times 90$


Fig 56.
$\times 90$

$\times 150$


Fig 58.
Fig 57.


Fig 60.



Fig 63.

Geometrical Growth Patterns.


Fig 64. A group of dislocations arranged along a line.


Fig 65. Group of dislocations giving a repeat pattern.
40.


Fig 66. Several groups of dislocations
interacting with one another
giving rise to a complex pattern.


Fig 67. Iwo intersecting groups of
circular spirals.


Fig 68. A number of dislocations at the centre. The growth steps bunch together away from the centre.


Fig 69. Circular spirals with bunching of steps. 42.

SPIRALS ORIGINATING FROM DISLOCATIONS

OF MULTIPLE STRENGTH

AND

MULTIPIङ DISLOCATIONS


Fig 70. Spiral originating from a dislocation of multiple strength (bright field illumination).

$\times 90$
Fig 7l. Right half of fig 70 showing dissociation of steps.



Fig 73A. Behaviour of steps further on the left of fig.73.


Fig 74. Dissociation of steps on alternate edges of hexagonal spiral.


Fig 75. A pair of spirals touching each other on one edge.


Fig 76. A trigonal spiral with rounded corners. 46

$\times 90$
Fig 77. Showing part of fig. 78.


Fig 78. Multiple dislocations showing the straight edges in three orientations of the outermost (or bottom) layers.


Fig 79. Multiple dislocations with faster growth at corners.

$\times 90$
Fig 80. Nultiple dislocations with straight edges of growth steps.

INTERLACED SPIRALS


Interlinking of four simple interlaced spirals; fig. 81 is the usual phase-contrast micrograph whereas fig. 82 had impurity smeared on it which gives this high visibility.


Fig 84. Illustrating the phenomenon of domination for interlaced spirals. The dominated dislocation is towards the left of the centre and lies on the 8th., edge from the first widely spaced turns. 50.


Fig 85. Illustrating several interlaced spirals, (bright field illumination).


Fig 86. The lower part of fig 85.
51.


Fig 87. Schematic representation of the interlacing of edges. $S$ represents the slowest $F$ the fastest monolayer in the stack.


Fig 88.


Fig 89 .

Double interlaced trigonal spirals.



An example of interlaced spiral with faster growth at corners producing a cusp in the middle of the straight edges.


Fig 94. showing the centre of figs. 92 and 93. The edges at the centre are seen to be convex.

## Grouped Interlaced Spirals.



Fig 95.

## $\times 300$



## $\times 300$

Grouping of seven steps together. Deposition of impurity
is seen on the step lines of fig.96, to lead to high visibility. 56.


Fig 97. Interaction of the advancing groups of seven layers with three interlaced spirals.

$\times 90$
Fig 98. Showing the centre of the grouped spirals.


Fig 99. Interlaced spiral with five steps grouping together.


Fig 100. Interlaced spiral with varying number of steps grouping together.


Fig l01. A double spiral observed on Si-C crystal type 33R.


Fig 102. Fizeau fringes passing over the spiral steps of fig lol. Fourth fringe from the top passes over the centre of the spiral.


Fig 103. showing superposition of figs. 101 and 102.


Fig 104. showing the centre of fig. 70.


Fig 105. Fizeau fringes passing over fig. 70 by using a lightly silvered glass flat.

Fig 106. Same as ing. 40.

Fig 107. Fizeau fringes passing over iig. 106. 62.


[^0]:    * Communicatd by Pofessor S. Tolansky.

[^1]:    p. 23

